

## Fuzzy Parameterized Fuzzy Soft Compact Spaces with Decision-Making

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**Abstract.** Some novel concepts including fuzzy parameterized fuzzy soft neighborhood germ,  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -S-neighborhood,  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -Lindelöf property and  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ - $\Omega$  accumulation point of  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -compact spaces are demonstrated with some important results. We delineate dual  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -point and the Bolzano Weierstrass property for  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -sets. We introduce modified form of an algorithm based on  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -compact topological space to the decision-making problem.

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**Key Words:**  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -neighborhood germ,  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -S-neighborhood, dual  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -point, countability of  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -space,  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ - $\Omega$ -accumulation point,  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -Lindelöf space, countable  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -compact space, Bolzano Weierstrass property for  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -space, decision-making.

### 1. INTRODUCTION

The property of being a "bounded set in a metric space is not conserved by homeomorphisms. So to generalize theorems in Real analysis like a continuous function on a closed bounded interval is bounded we need a new concept. This is the idea of compactness. Geometrically speaking, in finite dimensions, compact sets are those sets that are closed and bounded. This fundamentally means that, in a certain sense, they can't have infinite structure, which is a desirable feature to have. Most of the problems in engineering, medical science, economics, environments etc. have various uncertainties". To deal with uncertainties there are different theories including, fuzzy set theory introduced by Zadeh [42], soft set theory introduced by Molodtsov [23], fuzzy soft set theory ( $\mathfrak{f}\mathfrak{s}$ -set) introduced by Maji *et al.*

[25] and fuzzy parameterized fuzzy soft set theory (fpfs-set) [15, 41] introduced by Cagman *et al.* Intuitionistic fuzzy set (if-set) introduced by Atanassov [10] as an abstraction of fuzzy set and intuitionistic fuzzy soft set (ifss-set) was introduced by Maji *et al.* [24] as an abstraction of fuzzy soft set. Chang [14] in (1968) introduced fuzzy topology by using fuzzy sets. Abbas *et al.* [1] presented upper and lower contra-continuous fuzzy Multi-functions. Akram *et al.* [2, 3, 4, 5] introduced certain types of soft graphs and novel applications of m-polar fuzzy hypergraphs. Aslam and Riaz [8, 9] studied G-subsets and G-orbits of under action of the Modular Group. Cagman *et al.* [16, 17, 18] proposed soft topology, FS-set theory, fpfs-set theory and presented some applications to decision-making problems. Maji *et al.* [24, 25, 26, 27] introduced intuitionistic fuzzy soft sets, fuzzy soft sets, operations on Soft sets and application of soft sets in decision making problem. Riaz *et al.* [31, 32, 33, 34, 35] introduced some concepts of soft sets together with soft algebra, soft  $\sigma$ -algebra, soft  $\sigma$ -ring and measurable soft mappings. They found certain properties of soft metric spaces and studied fpfs-set and fpfs-topology with some important propositions and inaugurated certain applications of fpfs-set to the decision-making problems. Zorlutuna and Atmaca [41] presented fpfs-topology with some important results and fpfs-mappings. Zimmermann [43] established some applications of FS-set theory. Fuzzy set theory, soft set theory, fuzzy soft set theory with applications to the decision-making have studied in the last decade (See [6, 7, 11, 12, 13, 19, 20, 21, 22, 25, 28, 29, 30, 36, 37, 38, 39, 40]). "We have extended some ideas in the present work. We have continued to study the fpfs-compact spaces. We introduce some new concepts for fpfs-compact space such as fpfs-neighborhood germ, fpfs-S-neighborhood, dual fpfs-point and countability of fpfs-space. Moreover, we present fpfs- $\Omega$ -accumulation point, fpfs-Lindelöf space and Bolzano Weierstrass property for fpfs-space. We establish an application of fpfs-compact space to the decision-making problem. This paper can form the striking foundation for further applications of fpfs-topology on fpfs-sets".

## 2. PRELIMINARIES

In this section, we recall some basic ideas of fpfs-topology. Throughout this paper  $X$  represent initial universe and  $R$  represent the set of decision variables or attributes.

**Definition 2.1.** [15, 41] "Let  $X$  be the universal set and  $\tilde{P}(X)$  be the set of all fuzzy subsets of  $X$ , i.e.  $\tilde{P}(X)$  is the set  $[0, 1]^X$  of all functions from  $X$  to  $[0, 1]$ ,  $R$  be the set of attributes and  $A \subseteq R$ . A fuzzy parameterized fuzzy soft set (fpfs-set) is characterized by multivalued mapping  $\gamma_A : A \rightarrow \tilde{P}(X)$  such that  $\gamma_A(\varpi) = \phi$  if  $\mu_A(\varpi) = 0$  for  $\varpi \in A \subseteq R$ . The fpfs-set is denoted and defined by

$$F_A = \{(\mu_A(\varpi)/\varpi, \gamma_A(\varpi)) : \varpi \in A \subseteq R, \gamma_A(\varpi) \in \tilde{P}(X); \mu_A(\varpi), \gamma_A(\varpi)(\vartheta) \in [0, 1], \vartheta \in X\}.$$

The value  $\gamma_A(\varpi)$  is a fuzzy set known as  $\varpi$ -element of fpfs-set  $F_A \forall \varpi \in A \subseteq R$ , where  $\mu_A(\varpi)$  and  $\gamma_A(\varpi)(\vartheta)$  are the degrees of memberships of elements of set  $A \subseteq R$  and universal set  $X$  respectively".

**Definition 2.2.** [15, 41] "Let  $F_A$  be an fpfs-set over  $X$ . If  $\gamma_A(\varpi) = \phi \forall \varpi \in R$  i.e.  $\gamma_A(\varpi)$  is an empty fuzzy set for each parameter  $\varpi$ , then  $F_A$  is known as  $A$ -empty fpfs-set. It is represented as  $F_{\phi_A}$ . If  $A = \phi$ , then  $A$ -empty fpfs-set is called empty fpfs-set denoted as  $F_{\phi}$ ".

**Definition 2.3.** [15, 41] "Let  $F_A$  be an  $\text{fpfs}$ -set over  $X$ . If  $\gamma_A(\varpi) = X$  and  $\mu_A(\varpi) = 1 \forall \varpi \in R$  then  $F_A$  is known as  $A$ -universal  $\text{fpfs}$ -set and it is represented as  $F_{\tilde{A}}$ . If  $A = R$ , then  $A$ -universal  $\text{fpfs}$ -set is said to be universal or absolute  $\text{fpfs}$ -set and it is written as  $F_{\tilde{R}}$ ".

Now we present the definition of  $\text{fpfs}$ -topology by using elementary operations for  $\text{fpfs}$ -sets as given in [15, 41]. We use tilde  $\sim$  for these operations in  $\text{fpfs}$ -set theory to differentiate from crisp set theory.

**Definition 2.4.** [34, 41] Let  $F_{\tilde{R}}$  be an absolute  $\text{fpfs}$ -set and  $\text{fpfs}(F_{\tilde{R}})$  is the family of all  $\text{fpfs}$ -subsets of  $F_{\tilde{R}}$ . Let  $\tilde{\tau}$  be a subfamily of  $\text{fpfs}(F_{\tilde{R}})$  and  $A, B, C \subseteq R$ . Then  $\tilde{\tau}$  is known as  $\text{fpfs}$ -topology on  $F_{\tilde{R}}$  if the given conditions are satisfied:

- (i)  $F_\phi, F_{\tilde{R}} \in \tilde{\tau}$ ,
- (ii) if  $F_A, F_B \in \tilde{\tau}$  then  $F_A \cap F_B \in \tilde{\tau}$ ,
- (iii) if  $(F_C)_\lambda \in \tilde{\tau}, \forall \lambda \in J, J$  is arbitrary indexing set, then  $\bigcup_{\lambda \in J} (F_C)_\lambda \in \tilde{\tau}$ .

Members of  $\tilde{\tau}$  are known as  $\text{fpfs}$ -open sets and  $\text{fpfs}$ -complement of  $\text{fpfs}$ -open set is called  $\text{fpfs}$ -closed set.

**Definition 2.5.** [34, 41] An  $\text{fpfs}$ -set  $F_A$  is said to be an  $\text{fpfs}$ -point, denoted by  $\varpi(F_A)$ , if  $A \subseteq R$  is singleton fuzzy subset given as  $A = \{\mu_{F_A}(\varpi)/\varpi : \varpi \in R\}$  and  $F(\mu_{F_A}(\varpi)/\varpi) = \gamma_{F_A}^\varpi(\vartheta)$  is the image of  $A$  under multivalued mapping which is always a fuzzy set. Such that  $\gamma_{F_A}^\varpi(\vartheta) \neq \phi$  and  $F(\mu(\hat{\varpi})/\hat{\varpi}) = \phi, \forall \hat{\varpi} \in R \setminus \{\varpi\}$ .

**Example 2.6.** Let  $X = \{\vartheta_1, \vartheta_2, \vartheta_3\}$  be the universal set and let  $R = \{\varpi_1, \varpi_2, \varpi_3, \varpi_4\}$  be the set of attributes. If  $B = \{0.3/\varpi_1, 0.7/\varpi_2, 0.9/\varpi_4\} \subseteq R$ , where  $B$  the function represented as  $B : R \rightarrow [0, 1]$  i.e.  $B$  is a fuzzy subset of  $R$ . Similarly  $A$  is a fuzzy subset of  $R$ .

$A = \{0.1/\varpi_1\} \subseteq R$  with the  $\text{fpfs}$ -sets,  $F_B = \{(0.3/\varpi_1, \{0.1/\vartheta_1, 0.5/\vartheta_2, 0.3/\vartheta_3\}), (0.7/\varpi_2, \{0.1/\vartheta_1, 0.2/\vartheta_2, 0.5/\vartheta_3\}), (0.9/\varpi_4, \{0.4/\vartheta_1, 0.3/\vartheta_2, 0.6/\vartheta_3\})\}$   
 $F_A = \{(0.1/\varpi_1, \{0.1/\vartheta_1, 0.3/\vartheta_2, 0.2/\vartheta_3\}), (0/\varpi_2, \{0/\vartheta_1, 0/\vartheta_2, 0/\vartheta_3\}), (0/\varpi_3, \{0/\vartheta_1, 0/\vartheta_2, 0/\vartheta_3\}), (0/\varpi_4, \{0/\vartheta_1, 0/\vartheta_2, 0/\vartheta_3\})\}$   
 then  $\varpi(F_A)$  is called  $\text{fpfs}$ -point of  $F_B$ . Clearly  $\mu_{F_A}(\varpi) \leq \mu_{F_B}(\varpi); \forall \varpi \in R$  and  $\gamma_{F_A}^\varpi(\vartheta) \leq \gamma_{F_B}^\varpi(\vartheta); \forall \vartheta \in X$ . So,  $\varpi(F_A) \in F_B$ .

**Definition 2.7.** [34, 41] Let  $\varpi(F_{A_1})$  and  $F_{A_2} \in \text{fpfs}(F_{\tilde{R}})$ . Then  $\varpi(F_{A_1})$  is called  $\text{fpfs}$  quasi-coincident with  $F_{A_2}$  written as  $\varpi(F_{A_1}) q F_{A_2}$ , if  $\mu_{F_{A_1}}(\varpi) + \mu_{F_{A_2}}(\varpi) > 1; \varpi \in R$  and  $\gamma_{F_{A_1}}^\varpi(\vartheta) + \gamma_{F_{A_2}}^\varpi(\vartheta) > 1; \text{for some } \vartheta \in X$ . where  $\mu_{F_{A_1}}(\varpi)$  and  $\mu_{F_{A_2}}(\varpi)$  are degrees of memberships for parameter  $\varpi$  in  $\varpi(F_{A_1})$  and  $F_{A_2}$  respectively. Similarly,  $\gamma_{F_{A_1}}^\varpi(\vartheta)$  and  $\gamma_{F_{A_2}}^\varpi(\vartheta)$  represent the degrees of memberships for elements  $\vartheta \in X$ .

If  $\varpi(F_{A_1})$  is not  $\text{fpfs}$  quasi-coincident with  $F_{A_2}$ , then we write  $\varpi(F_{A_1}) \bar{q} F_{A_2}$ .

**Example 2.8.** Let  $X = \{\vartheta_1, \vartheta_2, \vartheta_3\}$  be the set of universe and let  $R = \{\varpi_1, \varpi_2, \varpi_3, \varpi_4\}$  be the set of attributes. If  $A_1 = \{0.6/\varpi_1\} \subseteq R, A_2 = \{0.7/\varpi_1, 0.8/\varpi_4\} \subseteq R$  with the  $\text{fpfs}$ -point and  $\text{fpfs}$ -set,  
 $\varpi(F_{A_1}) = \{(0.6/\varpi_1, \{0.6/\vartheta_1, 0.7/\vartheta_2, 0.8/\vartheta_3\})\}$ ,  
 $F_{A_2} = \{(0.7/\varpi_1, \{0.6/\vartheta_1, 0.5/\vartheta_2, 0.8/\vartheta_3\}), (0.8/\varpi_4, \{0.7/\vartheta_1, 0.8/\vartheta_2, 0.9/\vartheta_3\})\}$  respectively,

then it is clear that  $\varpi(F_{A_1})$  is quasi-coincident with  $F_{A_2}$ .

As  $\mu_{F_{A_1}}(\varpi_1) + \mu_{F_{A_2}}(\varpi_1) > 1$ ;  $\varpi_1 \in R$  and  $\gamma_{F_{A_1}}^{\varpi_1}(\vartheta) + \gamma_{F_{A_2}}^{\varpi_1}(\vartheta) > 1$ ;  $\vartheta \in X$ .

**Definition 2.9.** [34, 41] Let  $F_{A_1}$  and  $F_{A_2} \in \text{fpfs}(F_{\tilde{R}})$ . Then  $F_{A_1}$  is called fpfs quasi-coincident with  $F_{A_2}$  written as  $F_{A_1}qF_{A_2}$ , if

$\mu_{F_{A_1}}(\varpi) + \mu_{F_{A_2}}(\varpi) > 1$ ;  $\varpi \in A_1 \tilde{\cap} A_2$  and  $\gamma_{F_{A_1}}^{\varpi}(\vartheta) + \gamma_{F_{A_2}}^{\varpi}(\vartheta) > 1$ ;  $\vartheta \in X$ .

If  $F_{A_1}$  is not fpfs quasi-coincident with  $F_{A_2}$ , then we write  $F_{A_1}\bar{q}F_{A_2}$ .

**Definition 2.10.** [34] An fpfs-set  $F_{A_1}$  is called Q-neighborhood of  $\varpi(F_{A_2})$  if and only if there exists  $F_B \tilde{\in} \tau$  such that

$\varpi(F_{A_2})qF_B$  and  $F_B \tilde{\subseteq} F_{A_1}$ .

**Definition 2.11.** [34] An fpfs-point  $\varpi(F_A)$  is known as an adherence point of fpfs-set  $F_B$  iff every fpfs Q-neighborhood of  $\varpi(F_A)$  is a Q-coincident with  $F_B$ .

**Definition 2.12.** [41] Let  $(X, \tilde{\tau})$  be an fpfs-topological space and  $\text{fpfs}(F_{\tilde{R}}) = \{F_{A_\alpha} : \alpha \in \Omega\}$  be a collection of fpfs-subsets of  $F_{\tilde{R}}$ . Then the collection  $\text{fpfs}(F_{\tilde{R}})$  is said to satisfy the finite intersection property if every finite fpfs-sub-collection of  $\text{fpfs}(F_{\tilde{R}})$  has non-empty fpfs-intersection. That is, for any finite fpfs-subset  $\Omega_1$  of  $\Omega$ ,

$$\bigcap_{\beta \in \Omega_1} F_{A_\beta} \neq F_\phi$$

### 3. SOME RESULTS OF fpfs-COMPACT SPACE

In this section, we introduce some properties of fpfs-compact spaces. We establish various concepts for fpfs-compact space including, fpfs neighborhood germ, fpfs S-neighborhood, dual fpfs-point and countability of fpfs-space. Moreover, we define fpfs- $\Omega$ -accumulation point, fpfs-Lindelöf space and Bolzano Weierstrass property for fpfs-space.

**Definition 3.1.** An fpfs-set  $F_A$  in  $(X, \tilde{\tau})$  is called fpfs neighborhood of an fpfs-point  $\varpi(F_B)$  if and only if there exists a  $F_C \tilde{\in} (X, \tilde{\tau})$  such that  $\varpi(F_B) \tilde{\in} F_C \tilde{\subseteq} F_A$ ; an fpfs neighborhood  $F_A$  is said to be fpfs-open neighborhood if and only if  $F_A$  is fpfs-open set. The collection of all the fpfs neighborhoods of  $\varpi(F_B)$  is said to be a system of fpfs neighborhoods of  $\varpi(F_B)$ .

**Example 3.2.** Let  $X = \{\vartheta_1, \vartheta_2, \vartheta_3\}$  be the universal set and  $R = \{\varpi_1, \varpi_2, \varpi_3, \varpi_4\}$  be the set of parameters. If  $A_1 = \{0.2/\varpi_1, 0.4/\varpi_2, 0.3/\varpi_3\}$  and  $A_2 = \{0.2/\varpi_2, 0.1/\varpi_3\}$  are the fuzzy subsets of  $R$  then

$F_{A_1} = \{(0.2/\varpi_1, \{0.4/\vartheta_1, 0.2/\vartheta_2, 0.1/\vartheta_3\}), (0.4/\varpi_2, \{0.6/\vartheta_1, 0.7/\vartheta_2, 0.2/\vartheta_3\}),$

$(0.3/\varpi_3, \{0.3/\vartheta_1, 0.2/\vartheta_2, 0.4/\vartheta_3\})\}$  and

$F_{A_2} = \{(0.2/\varpi_2, \{0.4/\vartheta_1, 0.5/\vartheta_2, 0.1/\vartheta_3\}), (0.1/\varpi_3, \{0.3/\vartheta_1, 0.2/\vartheta_2, 0.2/\vartheta_3\})\}$  are fpfs-sets with the set of parameters  $A_1$  and  $A_2$  respectively.

Then  $\tilde{\tau} = \{F_\phi, F_{\tilde{R}}, F_{A_1}, F_{A_2}\}$  is an fpfs-topology.

Let  $\varpi(F_B) = \{(0.1/\varpi_2, \{0.3/\vartheta_1, 0.4/\vartheta_2, 0.1/\vartheta_3\})\}$  be an fpfs-point. For  $\varpi(F_B)$  there exists  $F_{A_2} \tilde{\in} \tilde{\tau}$  such that  $\varpi(F_B) \tilde{\in} F_{A_2} \tilde{\subseteq} F_{A_1}$ .

This implies that  $F_{A_1}$  is fpfs neighborhood of  $\varpi(F_B)$ . As  $F_{A_1}$  is fpfs-open set so  $F_{A_1}$  is called fpfs-open neighborhood of fpfs-point  $\varpi(F_B)$ .

**Proposition 3.3.** [41] Let  $\tilde{\tau}$  be an  $\text{fpfs}$ -topology on  $X$ . An  $\text{fpfs}$ -subfamily  $\mathbb{B}$  of  $\tilde{\tau}$  is an  $\text{fpfs}$ -base for  $\tilde{\tau}$  if and only if for each  $\text{fpfs}$ -point  $\varpi(F_A)$  in  $(X, \tilde{\tau})$  and for each  $\text{fpfs}$ -open  $Q$ -neighborhood  $F_B$  of  $\varpi(F_A)$ , there exists  $B \in \mathbb{B}$  such that  $\varpi(F_A)qB \in F_B$ .

**Definition 3.4.** Let  $\varpi(F_A)$  be an  $\text{fpfs}$ -point and  $\varpi(N_B)$  a fundamental  $\text{fpfs}$ -set in  $\text{fpfs}$ -topological space  $(X, \tilde{\tau})$ . If  $\varpi(F_A) \in \varpi(N_B)$ , then  $\varpi(N_B)$  is called an  $\text{fpfs}$  neighborhood germ of  $\varpi(F_A)$ .

**Theorem 3.5.** An  $\text{fpfs}$ -set  $F_A$  is an  $\text{fpfs}$  neighborhood of an  $\text{fpfs}$ -point  $\varpi(F_B)$  in  $\text{fpfs}$ -topological space  $(X, \tilde{\tau})$  if and only if there exist an open  $\text{fpfs}$ -set  $F_C \in \tilde{\tau}$  and an  $\text{fpfs}$  neighborhood germ  $\varpi(N_B)$  of  $\varpi(F_B)$  such that  $\varpi(F_B) \in \varpi(N_B) \tilde{C} F_C \tilde{C} F_A$ .

*Proof.* Consider an  $\text{fpfs}$  neighborhood  $F_A$  of an  $\text{fpfs}$ -point  $\varpi(F_B)$  in  $(X, \tilde{\tau})$  then by definition there exists an  $\text{fpfs}$ -open set  $F_C \in \tilde{\tau}$

$$\varpi(F_B) \in F_C \tilde{C} F_A \quad (3.1)$$

For any  $\varpi(N_B)$   $\text{fpfs}$  neighborhood germ of  $\varpi(F_B)$

$$\varpi(F_B) \in \varpi(N_B) \quad (3.2)$$

Combining above two equations (3.1), (3.2) we get

$$\varpi(F_B) \in \varpi(N_B) \tilde{C} F_C \tilde{C} F_A.$$

Conversely, suppose that there exists an  $\text{fpfs}$ -open set  $F_C \in \tilde{\tau}$  and an  $\text{fpfs}$  neighborhood germ  $\varpi(N_B)$  of  $\varpi(F_B)$  such that  $\varpi(F_B) \in \varpi(N_B) \tilde{C} F_C \tilde{C} F_A$ . Then from given relation we can write that  $\varpi(F_B) \tilde{C} F_C \tilde{C} F_A$ , which clearly shows that  $F_A$  is an  $\text{fpfs}$  neighborhood of an  $\text{fpfs}$ -point  $\varpi(F_B)$  in  $\text{fpfs}$ -topological space  $(X, \tilde{\tau})$ .  $\square$

**Definition 3.6.** An  $\text{fpfs}$ -set  $F_A$  is called  $\text{fpfs}$ -S-neighborhood of  $\text{fpfs}$ -point  $\varpi(F_B)$  in  $\text{fpfs}$ -topological space  $(X, \tilde{\tau})$  if and only if there is an  $\text{fpfs}$  neighborhood germ  $\varpi(N_B)$  of  $\varpi(F_B)$  and an  $\text{fpfs}$ -open set  $F_C$  such that  $\varpi(F_B) \in \varpi(N_B) \tilde{C} F_C \tilde{C} F_A$ .

**Definition 3.7.** Let  $\varpi(F_B)$  be an  $\text{fpfs}$ -point, then  $[\varpi(F_B)]^c$  is said to be dual  $\text{fpfs}$ -point of  $\varpi(F_B)$  and denoted as  $\varpi(F_B^d)$ .

**Remark:** The  $\text{fpfs}$ -Q-neighborhood of an  $\text{fpfs}$ -point is the  $\text{fpfs}$  neighborhood of its dual  $\text{fpfs}$ -point.

**Proposition 3.8.** Let  $F_A$  be an  $\text{fpfs}$ -set in  $\text{fpfs}$ -topological space  $(X, \tilde{\tau})$  and  $\varpi(F_B)$  be an  $\text{fpfs}$ -point. Every  $\text{fpfs}$  neighborhood of its dual  $\text{fpfs}$ -point  $\varpi(F_B^d)$  is  $\text{fpfs}$ -quasi-coincident with  $F_A$  if and only if  $\varpi(F_B) \in \overline{F_A}$ .

*Proof.* The Proof is similar to 4.15 of [34].  $\square$

**Theorem 3.9.** The  $\text{fpfs}$ -point  $\varpi(F_B) \in F_A^o$  if and only if its dual  $\text{fpfs}$ -point  $\varpi(F_B^d) \notin \overline{F_A^c}$ .

*Proof.* If  $\varpi(F_B^d) \notin \overline{F_A^c}$ , then there is an  $\text{fpfs}$  neighborhood  $F_C$  of  $\varpi(F_B^d)$   $\text{fpfs}$ -quasi-coincident with  $(F_A)^c$ , i.e.  $F_C \tilde{C} F_A$  and so  $\varpi(F_B) \in F_C \tilde{C} F_A$ , hence  $\varpi(F_B) \in F_A^o$ .

Conversely, if  $\varpi(F_B) \in F_A^o$  then there is  $F_C \in \tilde{\tau}$  such that

$\varpi(F_B) \in F_C \tilde{C} F_A$ ; i.e.  $F_C$  is not  $\text{fpfs}$ -quasi-coincident with  $F_A^c$  (or  $F_C$  and  $F_A^c$  are  $\text{fpfs}$ -quasi-incoincident), hence  $\varpi(F_B^d) \notin \overline{F_A^c}$ .  $\square$

**Definition 3.10.** Let  $\Omega_Q$  be an  $\text{fpfs-Q}$ -neighborhood system of a  $\text{fpfs}$ -point  $\varpi(F_A)$  in  $(X, \tilde{\tau})$ . A  $\text{fpfs}$ -subfamily  $B_Q$  of  $\Omega_Q$  is called a  $\text{fpfs-Q}$ -neighborhood base of  $\Omega_Q$  if and only if for each  $F_B \in \Omega_Q$  there exists  $F_C \in B_Q$  such that  $F_C \subset F_B$ .

**Definition 3.11.** An  $\text{fpfs}$ -topological space  $(X, \tilde{\tau})$  satisfy the  $\text{fpfs-Q}$ -first axiom of countability or to be  $\text{fpfs-Q-C}_1$  if and only if every  $\text{fpfs}$ -point in  $(X, \tilde{\tau})$  has an  $\text{fpfs-Q}$ -neighborhood base which is countable. Otherwise  $(X, \tilde{\tau})$  is  $\text{fpfs-C}_2$ -space.

**Remark:** If  $(X, \tilde{\tau})$  is  $\text{fpfs-C}_2$ -space, then it is also  $\text{fpfs-Q-C}_1$ -space but may or may not be  $\text{fpfs-C}_1$ -space.

**Proposition 3.12.** An  $\text{fpfs}$ -point  $\varpi(F_A) \in (F_B)^\circ$  if and only if there exists an  $\text{fpfs}$  neighborhood of  $\varpi(F_A)$  which contained in  $(F_B)^\circ$ .

*Proof.* The proof is straight forward.  $\square$

**Theorem 3.13.** (a)  $F_A^\circ = \overline{[(F_A^c)]^c}$ ,

(b)  $\overline{F_A} = [(F_A^c)^\circ]^c$ ,

(c)  $(\overline{F_A})^c = (F_A^c)^\circ$ ,

(d)  $\overline{F_A^c} = (F_A^\circ)^c$ .

*Proof.* (a) Let  ${}^\circ F_A = \{F_{A_\alpha} : \alpha \in \Omega \text{ and } F_{A_\alpha} \subset F_A\}$  be the collection of  $\text{fpfs}$ -open sets; then  $F_A^\circ = \bigcup {}^\circ F_A$ . Evidently,  ${}^\circ F_A^c = \{F_A^c : F_{A_\alpha} \in {}^\circ F_A\}$  is the collection of all  $\text{fpfs}$ -closed sets containing  $F_A^c$  and hence  $\overline{F_A^c} = \bigcap {}^\circ F_A^c$ . By using De Morgan's law, we can write that

$$\overline{F_A^c} = [\bigcap ({}^\circ F_A^c)]^c = \bigcup [(F_A^c)^\circ] = \bigcup (F_A^\circ) = F_A^\circ.$$

The proof is similar for the remaining parts of the theorem.  $\square$

**Proposition 3.14.** The derived set of each  $\text{fpfs}$ -set is  $\text{fpfs}$ -closed if and only if the derived set of every  $\text{fpfs}$ -point is  $\text{fpfs}$ -closed.

**Definition 3.15.** An  $\text{fpfs}$ -point  $\varpi(F_A)$  is called a  $\text{fpfs-}\Omega$ -accumulation point of  $F_B$  if and only if the  $\text{fpfs}$ -set consisting of all the  $\text{fpfs}$ -points at each of which every  $\text{fpfs-Q}$ -neighborhood of  $\varpi(F_A)$  and  $F_B$  are  $\text{fpfs}$ -quasi-coincident is uncountable.

**Definition 3.16.** Let  $F_A$  be an  $\text{fpfs}$ -set in  $(X, \tilde{\tau})$ . It satisfy  $\text{fpfs-Lindel}\ddot{o}$ f property if and only if every  $\text{fpfs}$ -open cover of  $F_A$  has a subcover which is countable.

$(X, \tilde{\tau})$  is said to be hereditarily  $\text{fpfs-Lindel}\ddot{o}$ f space if and only if every  $\text{fpfs}$ -set in  $X$  has the  $\text{fpfs-Lindel}\ddot{o}$ f property.

**Proposition 3.17.** If  $(X, \tilde{\tau})$  is  $\text{fpfs-C}_2$ -space then it is hereditarily  $\text{fpfs-Lindel}\ddot{o}$ f space.

**Definition 3.18.** [41] The family of  $\text{fpfs}$ -sets  ${}^\circ F_A$  is an  $\text{fpfs}$ -cover for a  $\text{fpfs}$ -set  $F_B$  if and only if  $F_B \subset \bigcup \{F_A : F_A \in {}^\circ F_A\}$ . If each member of  ${}^\circ F_A$  is  $\text{fpfs}$ -open set then it is an  $\text{fpfs}$ -open cover. An  $\text{fpfs}$ -subcover of  ${}^\circ F_A$  also an  $\text{fpfs}$ -cover.

**Definition 3.19.** [41] An  $\text{fpfs}$ -topological space  $X$  is  $\text{fpfs}$ -compact if and only if each  $\text{fpfs}$ -open cover of  $F_{\tilde{R}}$  has a finite  $\text{fpfs}$ -subcover. An  $\text{fpfs}$ -subspace  $(Y, E)$  of  $(X, \tilde{\tau})$  is said to be  $\text{fpfs}$ -compact if  $Y$  with relative  $\text{fpfs}$ -topology is compact.

**Example 3.20.** (i) [41] Let  $X = \{\vartheta_1, \vartheta_2, \dots\}$  be the universal set and  $R = \{\varpi_1, \varpi_2, \dots\}$  be the set of parameters. We define an  $\text{fpfs}$ -set

$$F_{A_n} = \left\{ \left( \frac{1}{\varpi_1}, \left\{ \frac{1}{\vartheta_1} \right\} \right), \left( \frac{1/2}{\varpi_2}, \left\{ \frac{1}{\vartheta_1}, \frac{1/2}{\vartheta_2} \right\} \right), \dots, \left( \frac{1/n}{\varpi_n}, \left\{ \frac{1}{\vartheta_1}, \frac{1/2}{\vartheta_2}, \dots, \frac{1/n}{\vartheta_n} \right\} \right) : n = 1, 2, 3, \dots \right\}$$

Then  $\tau = \{F_{A_n} : n = 1, 2, 3, \dots\} \tilde{\cup} \{F_\phi, F_{\tilde{R}}\}$  is an  $\text{fpfs}$ -topology on  $X$  and  $(X, \tilde{\tau})$  is  $\text{fpfs}$ -compact.

(ii) Any  $\text{fpfs}$ -topological space  $(X, \tilde{\tau})$  where either  $F_{\tilde{R}}$  is finite or  $\tilde{\tau}$  consists of a finite number of elements is  $\text{fpfs}$ -compact. This is so because, in this case, every  $\text{fpfs}$ -open cover of  $F_{\tilde{R}}$  is finite. Every  $\text{fpfs}$ -subspace of such a space is also  $\text{fpfs}$ -compact.

**Proposition 3.21.** [41] Let  $(X, \tilde{\tau})$  and  $(Y, \tilde{\tau}')$  be  $\text{fpfs}$ -topological spaces and  $f_{up} : (X, \tilde{\tau}) \rightarrow (Y, \tilde{\tau}')$  be an  $\text{fpfs}$ -mapping. If  $(X, \tilde{\tau})$  is  $\text{fpfs}$ -compact and  $f_{up}$  is  $\text{fpfs}$ -continuous surjection, then  $(Y, \tilde{\tau}')$  is  $\text{fpfs}$ -compact.

**Theorem 3.22.**  $\text{fpfs}$ -compact subset of  $\text{fpfs}$ -hausdorff space is  $\text{fpfs}$ -closed.

*Proof.* Let  $(X, \tilde{\tau})$  be an  $\text{fpfs}$ - $T_2$ -space and  $F_A$  be a  $\text{fpfs}$ -compact subset of  $(X, \tilde{\tau})$ . We will show that  $F_A^c$  is  $\text{fpfs}$ -open. For this let  $\varpi(F_B) \tilde{\in} F_A^c$ . Let  $\varpi(F_C)$  be any arbitrary  $\text{fpfs}$ -element of  $F_A$ , then  $\varpi(F_B) \neq \varpi(F_C)$ . Since  $(X, \tilde{\tau})$  is  $\text{fpfs}$ -hausdorff space, there are  $\text{fpfs}$ -open sets  $F_D$  and  $F_E$  in  $(X, \tilde{\tau})$  containing  $\varpi(F_B)$  and  $\varpi(F_C)$  respectively such that

$$F_D \tilde{\cap} F_E = F_\phi$$

The collection  $\{F_E \tilde{\cap} F_A : \varpi(F_C) \tilde{\in} F_A\}$  is a  $\text{fpfs}$ -open cover of  $F_A$ . Since  $F_A$  is  $\text{fpfs}$ -compact, then there exists an  $\text{fpfs}$ -open cover for  $F_A$  given as

$$\{F_{E_i} \tilde{\cap} F_A : i = 1, 2, 3, \dots, n\}$$

Now corresponding to each  $E_i$ , let  $F_{DE_i}$  be the  $\text{fpfs}$ -open set containing  $\varpi(F_B)$ .

Then  $U_D = \bigcap_{i=1}^n F_{DE_i}$  is  $\text{fpfs}$ -open, contains  $\varpi(F_B)$  and

$$\begin{aligned} U_D \tilde{\cap} F_A &= U_D \tilde{\cap} \bigcup_{i=1}^n (F_{E_i} \tilde{\cap} F_A) \\ &\tilde{\subseteq} U_D \tilde{\cap} \bigcup_{i=1}^n (F_{E_i}) \\ &\tilde{\subseteq} \bigcup_{i=1}^n (U_D \tilde{\cap} F_{E_i}) = F_\phi \quad \because F_{DE_i} \tilde{\cap} F_{E_i} = F_\phi \end{aligned}$$

Hence  $\varpi(F_B) \tilde{\in} U_D \tilde{\subseteq} F_A^c$ . This implies that  $F_A^c$  is  $\text{fpfs}$ -open. Thus  $F_A$  is  $\text{fpfs}$ -closed.  $\square$

**Theorem 3.23.** Let  $(X, \tilde{\tau})$  be an  $\text{fpfs}$ -Hausdorff space  $F_A$  a  $\text{fpfs}$ -compact subset of  $(X, \tilde{\tau})$  and  $\varpi(F_B)$  be a  $\text{fpfs}$ -element of  $(X, \tilde{\tau})$  and  $\varpi(F_B) \bar{q} F_A$ . Then there are disjoint  $\text{fpfs}$ -open sets  $F_C$  and  $F_D$  in  $(X, \tilde{\tau})$  such that

$$\varpi(F_B) \tilde{\in} F_C \text{ and } F_A \tilde{\subseteq} F_D$$

*Proof.* Suppose that  $F_A$  is an  $\text{fpfs}$ -compact subset of  $(X, \tilde{\tau})$  and  $\varpi(F_B) \tilde{\in} F_A^c$ . For each  $\varpi(F_G) \tilde{\in} F_A$ ,  $\varpi(F_G) \neq \varpi(F_B)$ , since  $(X, \tilde{\tau})$  is  $\text{fpfs}$ -Hausdorff, there are  $\text{fpfs}$ -open sets  $F_{GB}$  and  $F_G$  such that

$$\varpi(F_B) \tilde{\in} F_{GB}, \varpi(F_G) \tilde{\in} F_G \text{ and } F_{GB} \tilde{\cap} F_G = F_\phi$$

Now  $\{F_G \tilde{\cap} F_A : \varpi(F_G) \tilde{\in} F_A\}$  is a  $\text{fpfs}$ -open cover for  $F_A$ . Since  $F_A$  is a  $\text{fpfs}$ -compact, this  $\text{fpfs}$ -open cover has a finite  $\text{fpfs}$ -sub-cover

$$F_{G_1} \tilde{\cap} F_A, F_{G_2} \tilde{\cap} F_A, \dots, F_{G_n} \tilde{\cap} F_A$$

Let  $F_{GB_1}, F_{GB_2}, F_{GB_3}, \dots, F_{GB_n}$  be the corresponding  $\text{fpfs}$ -open sets in  $(X, \tilde{\tau})$  containing  $\varpi(F_B)$ .

Take

$$F_C = \bigcap_{i=1}^n F_{GB_i} \text{ and } F_D = \bigcup_{i=1}^n F_{G_i}$$

Then

$$\varpi(F_B) \tilde{\in} F_C, F_A \tilde{\subseteq} F_D$$

and

$$\begin{aligned} F_C \tilde{\cap} F_D &= F_C \tilde{\cap} \left( \bigcup_{i=1}^n F_{G_i} \right) \\ &= \bigcup_{i=1}^n (F_C \tilde{\cap} F_{G_i}) = F_\phi. \end{aligned}$$

□

**Remark:** Any arbitrary  $\text{fpfs}$ -subset of an  $\text{fpfs}$ -compact space may not be an  $\text{fpfs}$ -compact.

**Theorem 3.24.** Every  $\text{fpfs}$ -closed subset of an  $\text{fpfs}$ -compact space is  $\text{fpfs}$ -compact.

**Remark:**  $\text{fpfs}$ -closed subset of a  $\text{fpfs}$ -compact Hausdorff space is itself  $\text{fpfs}$ -compact and  $\text{fpfs}$ -Hausdorff.

**Theorem 3.25.** Every  $\text{fpfs}$ -compact Hausdorff space is  $\text{fpfs}$ -normal.

*Proof.* Let  $(X, \tilde{\tau})$  be an  $\text{fpfs}$ -compact Hausdorff space and  $F_{A_1}, F_{A_2}$  be arbitrary two disjoint  $\text{fpfs}$ -closed subsets of  $(X, \tilde{\tau})$ . By Theorem 3.23 for any  $\varpi(F_B) \tilde{\in} F_{A_1}$  then there are  $\text{fpfs}$ -open sets  $F_B$  and  $F_D$  in  $(X, \tilde{\tau})$  such that

$$\varpi(F_B) \tilde{\in} F_B, F_{A_2} \tilde{\subseteq} F_D, F_B \tilde{\cap} F_D = F_\phi$$

The sets  $\{F_B : \varpi(F_B) \tilde{\in} F_{A_1}\}$  form a  $\text{fpfs}$ -open cover for  $F_{A_1}$ . Since  $F_{A_1}$  is  $\text{fpfs}$ -closed,  $F_{A_1}$  is  $\text{fpfs}$ -compact, so there are  $\text{fpfs}$ -elements  $\varpi(F_{B_1}), \varpi(F_{B_2}), \dots, \varpi(F_{B_n})$  such that

$$F_{A_1} \tilde{\subseteq} \bigcup_{i=1}^n F_{B_i}$$

Let

$$F_U = \bigcup_{i=1}^{\widetilde{n}} F_{B_i}, F_V = \bigcap_{i=1}^{\widetilde{n}} F_{D_i}$$

Then

$$F_{A_1} \widetilde{\subseteq} F_U, F_{A_2} \widetilde{\subseteq} F_V \text{ and } F_U \widetilde{\cap} F_V = F_\phi$$

Hence  $(X, \widetilde{\tau})$  is  $\text{fpfs-normal}$ . □

**Definition 3.26.** An  $\text{fpfs-topological space } (X, \widetilde{\tau})$  is countably  $\text{fpfs-compact}$  if and only if every countable  $\text{fpfs-open cover}$  has an  $\text{fpfs-subcover}$  which is finite.

**Remark:** Clearly, every  $\text{fpfs-compact space}$  is countably  $\text{fpfs-compact space}$ . This is so because if every  $\text{fpfs-open cover}$  of an  $\text{fpfs-space } (X, \widetilde{\tau})$  has an  $\text{fpfs-subcover}$  which is finite then every countable  $\text{fpfs-open cover}$  also has a finite  $\text{fpfs-subcover}$ .

**Theorem 3.27.** *Let  $(X, \widetilde{\tau})$  be an  $\text{fpfs-topological space}$ . Then every  $\text{fpfs-subset}$  of  $X$  which is countably infinite has an  $\text{fpfs-limit point}$  if and only if any infinite  $\text{fpfs-subset}$  of  $(X, \widetilde{\tau})$  has an  $\text{fpfs-limit point}$ .*

*Proof.* If every infinite  $\text{fpfs-subset}$  of a  $\text{fpfs-topological space}$  has an  $\text{fpfs-limit point}$  in  $(X, \widetilde{\tau})$  then it immediately follows that every countably infinite  $\text{fpfs-subset}$  of  $(X, \widetilde{\tau})$  also has an  $\text{fpfs-limit point}$  in  $(X, \widetilde{\tau})$ .

Conversely, suppose that every  $\text{fpfs-subset}$  of  $X$  which is countably infinite has an  $\text{fpfs-limit point}$  in  $(X, \widetilde{\tau})$ . Let  $F_A$  be any infinite  $\text{fpfs-subset}$  of  $(X, \widetilde{\tau})$ . Then  $F_A$  contains a countably infinite  $\text{fpfs-subset } F_B$

$$F_B = \left\{ \left( \frac{\mu_{F_B}(\varpi_i)}{\varpi_i}, \left\{ \frac{\gamma_{F_B}^{\varpi_i}(\vartheta_i)}{\vartheta_i} \right\} \right) : i, j = 1, 2, 3, \dots, n, \dots \right\}$$

By our assumption  $F_B$  has an  $\text{fpfs-limit point } \varpi(F_C)$  in  $(X, \widetilde{\tau})$ . But then  $\varpi(F_C)$  is also a  $\text{fpfs-limit point}$  of  $F_A$ . □

**Theorem 3.28.** *If  $(X, \widetilde{\tau})$  is a countably  $\text{fpfs-compact space}$ , then every  $\text{fpfs-subset}$  of  $(X, \widetilde{\tau})$  which is infinite has an  $\text{fpfs-limit point}$  in  $(X, \widetilde{\tau})$ .*

*Proof.* Suppose that  $F_A$  is any infinite  $\text{fpfs-subset}$  of a countably  $\text{fpfs-compact space } (X, \widetilde{\tau})$ . Then  $F_A$  has a countably infinite  $\text{fpfs-subset}$

$$F_B = \left\{ \left( \frac{\mu_{F_B}(\varpi_i)}{\varpi_i}, \left\{ \frac{\gamma_{F_B}^{\varpi_i}(\vartheta_i)}{\vartheta_i} \right\} \right) : i, j = 1, 2, 3, \dots, n, \dots \right\}$$

Suppose that  $F_A$  and therefore also  $F_B$ , has no  $\text{fpfs-limit point}$  in  $(X, \widetilde{\tau})$ . Consider the  $\text{fpfs-subsets}$

$$F_{C_P} = \left\{ \left( \frac{\mu_{F_{C_P}}(\varpi_n)}{\varpi_n}, \left\{ \frac{\gamma_{F_{C_P}}^{\varpi_n}(\vartheta_m)}{\vartheta_m} \right\} \right) : p, q = 1, 2, 3, \dots; n = p, p+1, \dots; m = q, q+1, \dots \right\}$$

Since the  $\text{fpfs-derived set}$  of every  $F_{C_P}, P = 1, 2, 3, \dots$  is  $\text{fpfs-empty}$ , so  $F_{C_P}$  are all  $\text{fpfs-closed}$ . Also  $\{F_{C_P}, P = 1, 2, 3, \dots\}$  satisfies the finite intersection property because

$$F_{C_{P_1}} \widetilde{\cap} F_{C_{P_2}} \widetilde{\cap} \dots \widetilde{\cap} F_{C_{P_k}} = F_{C_{P_0}} \neq F_\phi$$

where  $P_0 = \max(P_1, P_2, \dots, P_k)$ .

Now,

$$\bigcap_{p=1}^{\infty} F_{C_p} = F_\phi$$

for if an  $\text{fpfs}$ -point  $\varpi(F_{x_p})$  of  $F_B$  is in  $\bigcap_{p=1}^{\infty} F_{C_p}$ , then  $\varpi(F_{x_p}) \notin F_{C_{p-1}}$ . But then  $(X, \tilde{\tau})$  is not countably  $\text{fpfs}$ -compact, a contradiction. Hence  $F_B$  and therefore also  $F_A$ , has an  $\text{fpfs}$ -limit point in  $(X, \tilde{\tau})$ .  $\square$

**Definition 3.29.** An  $\text{fpfs}$ -space  $(X, \tilde{\tau})$  is said to satisfy the Bolzano-Weierstrass property if and only if every  $\text{fpfs}$ -subset of  $(X, \tilde{\tau})$  which is infinite has a  $\text{fpfs}$ -limit point in  $(X, \tilde{\tau})$ . Thus by Theorem 3.28 we can say that every countably  $\text{fpfs}$ -compact space satisfy the Bolzano-Weierstrass property.

**Proposition 3.30.** Let  $(X, \tilde{\tau})$  be an  $\text{fpfs}$ - $T_1$ -space. Then  $(X, \tilde{\tau})$  is countably  $\text{fpfs}$ -compact if and only if  $(X, \tilde{\tau})$  satisfy Bolzano-Weierstrass property.

#### 4. AN ALGORITHM FOR $\text{fpfs}$ -COMPACT SPACE TO DECISION-MAKING

Despite shooting excellent pictures using a quality digital camera, at times it's necessary to edit the pictures taken to suit your photography business. This is when driven by a desire to turn your image into an art or transforming it into a completely new image so it can seek attention. It is necessary to edit photos to increase their attractiveness and quality, hence improving their value. Photo editing may be applied so as to obscure or take out unwanted details that deprive focus away from the subject you wanted to underline. It is thus very significant to both professional and amateur photographers to learn photo editing skills and deliver the software itself to be able to contend with what is seen as the standard of photography now a days.

We have modified the algorithm used in [18] for  $\text{fpfs}$ -compact space.

##### Algorithm:

The algorithm which we will use in the given application is based on the following steps.

**step 1:** Construct an  $\text{fpfs}$ -compact space using universal set  $X$  and selected set of parameters .

**step 2:** Select some  $\text{fpfs}$ -open sets from the  $\text{fpfs}$ -compact space.

**step 3:** Find the fuzzy decision sets from all selected  $\text{fpfs}$ -open sets by using the formula given as

$$F_A^d = \{\gamma_{F_A^d}(\vartheta)/\vartheta : \vartheta \in X\}$$

where

$$\mu_{F_A^d}(\vartheta) = \frac{1}{|supp(A)|} \sum_{\varpi \in supp(A)} \mu_{F_A}(\varpi) \gamma_{F_A}^{\varpi}(\vartheta)$$

**step 4:** Add the all fuzzy decision sets by using fuzzy addition.

**step 5:** Find the largest choice value from the resultant set after fuzzy addition.

**Example 4.1.** A good graphic designer signed a contract for a marriage ceremony. After capturing the photographs, family assigned him to make a photo album of beautiful family pictures with better graphics. For editing the images and to make them graphically better he needs to use an image editing software. We constitute a new algorithm which helps him choose the best software that makes his task extremely easy and advance.

The set  $X = \{\vartheta_1, \vartheta_2, \vartheta_3, \vartheta_4, \vartheta_5, \vartheta_6, \vartheta_7, \vartheta_8, \vartheta_9, \vartheta_{10}, \vartheta_{11}, \vartheta_{12}, \vartheta_{13}, \vartheta_{14}, \vartheta_{15}\}$  represent the list of some image editing softwares, where

$\vartheta_1 = \text{CorelDRAW Graphics Suite X5}$ ,

$\vartheta_2 = \text{Adobe Indesign}$ ,

$\vartheta_3 = \text{Adobe Flash}$ ,

$\vartheta_4 = \text{Art Rage 3.5}$ ,

$\vartheta_5 = \text{Adobe photoshop}$ ,

$\vartheta_6 = \text{Wacom Tablets}$ ,

$\vartheta_7 = \text{Gimp}$ ,

$\vartheta_8 = \text{Paint.NET}$ ,

$\vartheta_9 = \text{Pixelmator}$ ,

$\vartheta_{10} = \text{5DFLY}$ ,

$\vartheta_{11} = \text{Skitch}$ ,

$\vartheta_{12} = \text{Adobe Illuster}$ ,

$\vartheta_{13} = \text{Picnik}$ ,

$\vartheta_{14} = \text{Fat Paint}$ ,

$\vartheta_{15} = \text{AutoCAD}$ .

The set of parameters,

$$R = \{\varpi_1, \varpi_2, \varpi_3, \varpi_4, \varpi_5, \varpi_6, \varpi_7, \varpi_8, \varpi_9, \varpi_{10}, \varpi_{11}\}$$

is the set of characteristics or qualities of softwares, where

$\varpi_1 = \text{capability}$ ,

$\varpi_2 = \text{security}$ ,

$\varpi_3 = \text{performance}$ ,

$\varpi_4 = \text{compatibility}$ ,

$\varpi_5 = \text{integrity}$ ,

$\varpi_6 = \text{flexibility}$ ,

$\varpi_7 = \text{modularity}$ ,

$\varpi_8 = \text{portability}$ ,

$\varpi_9 = \text{reusability}$ ,

$\varpi_{10} = \text{correctness}$ ,

$\varpi_{11} = \text{IT-bility}$ .

"There are many parameters which tell us about the importance and quality of image editing softwares but here we consider only eleven parameters because they are most important for image editing and enough to identify the quality of softwares. We can increase the number of attributes according to our choice or according to the given data for any decision-making problem.

He needs only six parameters "capability", "security", "flexibility", "portability", "reusability" and "IT-bility", which constitute a subset  $E$  of  $R$  given by

$$E = \{\varpi_1, \varpi_2, \varpi_6, \varpi_8, \varpi_9, \varpi_{11}\}.$$

We consider an  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -compact space on given set of parameters  $E$  and on  $X$ . We choose some  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -sets from  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -compact space according to the photographer's choice through which we can make the decision set. Suppose that  $(F_A)$  is the selected  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -set where  $A = \{0.8/\varpi_1, 0.6/\varpi_2, 0.7/\varpi_6, 0.5/\varpi_8, 0.4/\varpi_9\}$  is fuzzy subset of  $E$ . All the attributes are important, but here the attributes are chosen with the desire of photographer, because he knows well that how to make an album according to the customer's choice. All the values presented in the table are according to a survey, opinion and experience of some professional photographers".

The tabular form of  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -set  $F_A$  can be represented as

$F_A$	$0.8/\varpi_1$	$0.6/\varpi_2$	$0.7/\varpi_6$	$0.5/\varpi_8$	$0.4/\varpi_9$
$\vartheta_1$	0.2	0.3	0.2	0.1	0.1
$\vartheta_2$	0.4	0.2	0.4	0.3	0.3
$\vartheta_3$	0.1	0.4	0.1	0.2	0.2
$\vartheta_4$	0.2	0.1	0.2	0.3	0.3
$\vartheta_5$	0.9	0.9	0.9	0.9	0.9
$\vartheta_6$	0.4	0.4	0.4	0.3	0.3
$\vartheta_7$	0.3	0.4	0.3	0.3	0.3
$\vartheta_8$	0.1	0.2	0.1	0.2	0.2
$\vartheta_9$	0.6	0.6	0.6	0.5	0.6
$\vartheta_{10}$	0.2	0.3	0.2	0.2	0.2
$\vartheta_{11}$	0.4	0.1	0.2	0.3	0.5
$\vartheta_{12}$	0.8	0.8	0.8	0.8	0.8
$\vartheta_{13}$	0.1	0.2	0.1	0.1	0.1
$\vartheta_{14}$	0.7	0.7	0.7	0.7	0.7
$\vartheta_{15}$	0.1	0.1	0.1	0.1	0.1

Now we calculate the support of a fuzzy set A given as

$$\text{supp}(A) = \{\varpi : \mu(\varpi) \neq 0\}$$

where  $\mu(\varpi)$  denotes the degree of membership of the element  $\varpi$ . Clearly,  $\text{Supp}(A)$  is a crisp set. We can see that in above  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -set  $F_A$ ,  $\text{supp}(A) = \{\varpi_1, \varpi_2, \varpi_6, \varpi_8, \varpi_9\}$  which implies that  $|\text{supp}(A)| = 5$ .

The fuzzy decision set  $F_A^d$  of  $F_A$  can be calculated by using the given formulas

$$F_A^d = \{\gamma_{F_A^d}(\vartheta)/\vartheta : \vartheta \in X\}$$

where

$$\mu_{F_A^d}(\vartheta) = \frac{1}{|\text{supp}(A)|} \sum_{\varpi \in \text{supp}(A)} \mu_{F_A}(\varpi) \gamma_{F_A}^{\varpi}(\vartheta)$$

The above formulas are modified forms of the formulas used in [18] for  $\mathfrak{f}\mathfrak{p}\mathfrak{s}$ -set. We modify these formulas for  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -set.

$$F_A^d = \{0.114/\vartheta_1, 0.198/\vartheta_2, 0.114/\vartheta_3, 0.126/\vartheta_4, 0.54/\vartheta_5, 0.222/\vartheta_6, 0.192/\vartheta_7, 0.09/\vartheta_8, 0.35/\vartheta_9, 0.132/\vartheta_{10}, 0.174/\vartheta_{11}, 0.48/\vartheta_{12}, 0.072/\vartheta_{13}, 0.42/\vartheta_{14}, 0.06/\vartheta_{15}\}.$$

Suppose that  $(F_B)$  is the other  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -set which is selected,

here  $B = \{0.5/\varpi_1, 0.7/\varpi_2, 0.3/\varpi_6, 0.7/\varpi_8, 0.8/\varpi_9, 0.3/\varpi_{11}\}$  is fuzzy subset of  $E$ .

Thus the tabular form of  $\wp$ -set  $F_B$  can be represented as

$F_B$	$0.5/\varpi_1$	$0.7/\varpi_2$	$0.3/\varpi_6$	$0.7/\varpi_8$	$0.8/\varpi_9$	$0.3/\varpi_{11}$
$\vartheta_1$	0.2	0.3	0.2	0.1	0.1	0.1
$\vartheta_2$	0.4	0.2	0.4	0.3	0.3	0.3
$\vartheta_3$	0.1	0.4	0.1	0.2	0.2	0.2
$\vartheta_4$	0.2	0.1	0.2	0.3	0.3	0.3
$\vartheta_5$	0.9	0.9	0.9	0.9	0.9	0.9
$\vartheta_6$	0.4	0.4	0.4	0.3	0.3	0.3
$\vartheta_7$	0.3	0.4	0.3	0.3	0.3	0.3
$\vartheta_8$	0.1	0.2	0.1	0.2	0.2	0.2
$\vartheta_9$	0.6	0.6	0.6	0.5	0.6	0.6
$\vartheta_{10}$	0.2	0.3	0.2	0.2	0.2	0.2
$\vartheta_{11}$	0.4	0.1	0.2	0.3	0.5	0.5
$\vartheta_{12}$	0.8	0.8	0.8	0.8	0.8	0.8
$\vartheta_{13}$	0.1	0.2	0.1	0.1	0.1	0.1
$\vartheta_{14}$	0.7	0.7	0.7	0.7	0.7	0.7
$\vartheta_{15}$	0.1	0.1	0.1	0.1	0.1	0.1

As we can see that  $\text{supp}(B) = \{\varpi_1, \varpi_2, \varpi_6, \varpi_8, \varpi_9, \varpi_{11}\}$  which implies that  $|\text{supp}(B)| = 6$ .

Similarly by using the above method we can find out the fuzzy decision set  $F_B^d$  for  $F_B$ .

$$F_B^d = \{0.091/\vartheta_1, 0.166/\vartheta_2, 0.12/\vartheta_3, 0.1283/\vartheta_4, 0.495/\vartheta_5, 0.19/\vartheta_6, 0.176/\vartheta_7, 0.0966/\vartheta_8, 0.318/\vartheta_9, 0.121/\vartheta_{10}, 0.181/\vartheta_{11}, 0.44/\vartheta_{12}, 0.066/\vartheta_{13}, 0.385/\vartheta_{14}, 0.055/\vartheta_{15}\}.$$

Now we take sum of both fuzzy decision sets  $F_A^d$  and  $F_B^d$  according to fuzzy rules by using the given formula which is basically the addition of two fuzzy sets and was defined by Zadeh.

$$\gamma_{F_A^d + F_B^d}(\vartheta) = \gamma_{F_A^d}(\vartheta) + \gamma_{F_B^d}(\vartheta) - [\gamma_{F_A^d}(\vartheta) * \gamma_{F_B^d}(\vartheta)] \forall \vartheta \in X.$$

Which implies that

$$F_A^d + F_B^d = \{0.1947/\vartheta_1, 0.3312/\vartheta_2, 0.2204/\vartheta_3, 0.2382/\vartheta_4, 0.7677/\vartheta_5, 0.3699/\vartheta_6, 0.3343/\vartheta_7, 0.1779/\vartheta_8, 0.5567/\vartheta_9, 0.2370/\vartheta_{10}, 0.3235/\vartheta_{11}, 0.7088/\vartheta_{12}, 0.1332/\vartheta_{13}, 0.6433/\vartheta_{14}, 0.1117/\vartheta_{15}\}.$$

Finally, we pick out the largest degree of membership by

$$\max \gamma_{F_A^d + F_B^d}(\vartheta) = 0.7677$$

Which shows that the photographer should select  $\vartheta_5 =$  Adobe photoshop for editing the images and to make them graphically better. His second choice goes to  $\vartheta_{12} =$  Adobe Illuster and third choice goes to  $\vartheta_{14} =$  Fat Paint.

”This application is based on decision-making and tells us about our preferences. When the decision comes out then it does not means that some products are good or others are bad, infect it gives us first, second and third preferences based on our choice of attributes which help us to make our decisions correctly and beneficently. All the values given to the attributes tells us that how much the photographer needs that quality or parameter for his work and that values given by his own choice. Similarly in the table all the values given to the softwares tells us that how much a software has that quality or in what percentage that software contain the corresponding parameter and that values are calculated by a survey

and according to the opinion and experiences of some professional photographers. This application basically tells us how we can make our decision by using  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -sets, which was chosen from the  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -compact space”.

## 5. CONCLUSION

In this paper, we introduced  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$  neighborhood germ and  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -S-neighborhood. We premised some consequences on  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -compact topological space. We then presented a new algorithm for decision-making, which demonstrated that this method would be appreciated for the researchers. We can utilize the results derived from the studies on  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -compact space to meliorate the concepts. It can be spread over many areas of the problems that contain vagueness and would be valuable to offer the proposed method to subsequent written reports. We trust that the judgments in this report will be fruitful for the investigators to boost and advertise the further analysis on  $\mathfrak{f}\mathfrak{p}\mathfrak{f}\mathfrak{s}$ -topology to carry out a worldwide structure for their applications in virtual life.

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