

e–Chaotic Generalized Shift Dynamical Systems

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Abstract. In the following text we prove that for bijection $\varphi : \mathbb{N} \rightarrow \mathbb{N}$ and discrete set $\{1, \dots, k\}$ with $k \geq 2$, the generalized shift dynamical system $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_{\varphi})$ is *e*-chaotic, (expansive, positively expansive) if and only if $\{\{\varphi^i(n) : i \in \mathbb{Z}\} : n \in \mathbb{N}\}$ is a finite partition of \mathbb{N} (or equivalently there exists $N \in \mathbb{N}$ such that $\mathbb{N} = \bigcup\{\varphi^i(\{1, \dots, N\}) : i \in \mathbb{Z}\}$).

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1. PRELIMINARES

By a *topological dynamical system* (or briefly *dynamical system*) (X, f) we mean a topological space X (*phase space*) and continuous map $f : X \rightarrow X$.

For a nonempty set X consider two maps one-sided shift $\sigma_1 : X^{\mathbb{N}} \rightarrow X^{\mathbb{N}}$ and two-sided shift $\sigma_2 : X^{\mathbb{Z}} \rightarrow X^{\mathbb{Z}}$ with $\sigma_1((x_n)_{n \in \mathbb{N}}) = (x_{n+1})_{n \in \mathbb{N}}$ (for $(x_n)_{n \in \mathbb{N}} \in X^{\mathbb{N}}$) and $\sigma_2((y_n)_{n \in \mathbb{Z}}) = (y_{n+1})_{n \in \mathbb{Z}}$ (for $(y_n)_{n \in \mathbb{Z}} \in X^{\mathbb{Z}}$), where $\mathbb{N} = \{1, 2, \dots\}$ is the set of all natural numbers and $\mathbb{Z} = \{0, \pm 1, \pm 2, \dots\}$ is the set of all integers. One-sided and two-sided shifts are well-known and studied in several branches of mathematics, like ergodic theory and dynamical systems. For arbitrary nonempty set Γ , map $\varphi : \Gamma \rightarrow \Gamma$, nonempty set X with at least two elements, we call $\sigma_{\varphi} : X^{\Gamma} \rightarrow X^{\Gamma}$ with $\sigma_{\varphi}((x_{\alpha})_{\alpha \in \Gamma}) = (x_{\varphi(\alpha)})$ (for all $(x_{\alpha})_{\alpha \in \Gamma} \in X^{\Gamma}$) the *generalized shift*. If X is a topological space, consider X^{Γ} under product (pointwise convergence) topology, so $\sigma_{\varphi} : X^{\Gamma} \rightarrow X^{\Gamma}$ is continuous. Generalized shifts in the above form has been introduced in [3], and their dynamical (and non-dynamical) properties has been studied in several texts, like [1], [2] and [6].

REMARK 1. *Suppose X is a topological space with at least two elements and Γ is a nonempty set, equip X^{Γ} with product topology. It is well-known that [7]:*

- X^Γ is compact if and only if X is compact;
- X^Γ is metrizable if and only if X is metrizable and Γ is countable.

REMARK 2. Suppose X is a nonempty set with at least two elements and Γ is a nonempty set, then the following statements are equivalent [3]:

- $\sigma_\varphi : X^\Gamma \rightarrow X^\Gamma$ is bijective;
- $\varphi : \Gamma \rightarrow \Gamma$ is bijective.

Hence if X has a topological structure, then $\sigma_\varphi : X^\Gamma \rightarrow X^\Gamma$ is a homeomorphism if and only if $\varphi : \Gamma \rightarrow \Gamma$ is bijective.

REMARK 3. If Γ is a nonempty set and $\varphi : \Gamma \rightarrow \Gamma$ is arbitrary, for $\alpha, \beta \in \Gamma$ let $\alpha \sim_\varphi \beta$ if and only if there exists $n, m \in \mathbb{N}$ with $\varphi^n(\alpha) = \varphi^m(\beta)$. Then \sim_φ is an equivalence relation on X . If $\varphi : \Gamma \rightarrow \Gamma$ is bijective and $\alpha \in \Gamma$, then the equivalence class of α under φ is $\frac{\alpha}{\sim_\varphi} = \{\varphi^n(\alpha) : n \in \mathbb{Z}\}$, so $\frac{\alpha}{\sim_\varphi}$ has exactly one of the following forms:

- there exists $m \in \mathbb{N}$ with $\frac{\alpha}{\sim_\varphi} = \{\alpha_n : 0 \leq n < m\}$ where α_i 's are distinct $\varphi(\alpha_i) = \alpha_{i+1}$ for $i = 0, \dots, m-1$ and $\varphi(\alpha_{m-1}) = \alpha_0$;
- $\frac{\alpha}{\sim_\varphi} = \{\alpha_n : n \in \mathbb{Z}\}$, α_n s are distinct and $\varphi(\alpha_n) = \alpha_{n+1}$ for $n \in \mathbb{Z}$.

In addition for bijective $\varphi : \Gamma \rightarrow \Gamma$ and $\alpha, \beta \in \Gamma$ we have $\alpha \sim_\varphi \beta$ if and only if there exists $n \in \mathbb{Z}$ with $\varphi^n(\alpha) = \beta$.

In the following text suppose X is a discrete finite set with at least two elements and Γ is a countable infinite set. So we may suppose $X = \{1, \dots, k\}$ with discrete topology, $k \geq 2$, and $\Gamma = \mathbb{N}$, also suppose $\varphi : \Gamma \rightarrow \Gamma$ is bijective (note to Remarks 1 and 2). The main aim of this text is to study e -chaotic generalized shift dynamical system $(\{1, \dots, k\}^\mathbb{N}, \sigma_\varphi)$.

2. WHEN IS $(\{1, \dots, k\}^\mathbb{N}, \sigma_\varphi)$ EXPANSIVE?

We call the dynamical system (Y, f) (or briefly $f : Y \rightarrow Y$) with compact metric space (Y, ρ) and homeomorphism $f : Y \rightarrow Y$, *expansive* if there exists $\mu > 0$ such that for all distinct $x, y \in Y$ there exists $n \in \mathbb{Z}$ with $\rho(f^n(x), f^n(y)) > \mu$.

REMARK 4. For arbitrary set Y we call the collection \mathcal{F} of subsets of $Y \times Y$ a *uniform structure in Y* if (let $\Delta_Y = \{(x, x) : x \in Y\}$) [5]:

- $\forall \alpha \in \mathcal{F} (\Delta_Y \subseteq \alpha)$;
- $\forall \alpha, \beta \in \mathcal{F} (\alpha \cap \beta \in \mathcal{F})$;
- $\forall \alpha \in \mathcal{F} \exists \beta \in \mathcal{F} (\beta \circ \beta^{-1} \subseteq \alpha)$;
- $\forall \alpha \in \mathcal{F} \forall \beta \subseteq Y \times Y (\alpha \subseteq \beta \Rightarrow \beta \in \mathcal{F})$.

Moreover for all $\alpha \in \mathcal{F}$ and $x \in Y$ let $\alpha[x] = \{y \in Y : (x, y) \in \alpha\}$.

If \mathcal{F} is a uniform structure in Y , then $\{U \subseteq Y : \forall x \in Y \exists \alpha \in \mathcal{F} (\alpha[x] \subseteq U)\}$ is a topology on Y , we call it *uniform topology induced from \mathcal{F}* . We call the topological space *uniformizable* if there exists a uniform structure \mathcal{F} in Y such that uniform topology induced from \mathcal{F} coincides with original topology on Y , and in this case we call \mathcal{F} *compatible uniform structure in Y* . Every compact Hausdorff (resp. compact metric) space is uniformizable and has a unique compatible uniform structure. If Y is a compact metric space, for $\varepsilon > 0$ let $\alpha_\varepsilon = \{(x, y) \in Y \times Y : \rho(x, y) \leq \varepsilon\}$, and $\mathcal{G} = \{D \subseteq Y \times Y : \exists \delta > 0 (\alpha_\delta \subseteq D)\}$, then \mathcal{G} is a compatible uniform structure in Y . It's evident that homeomorphism $f : Y \rightarrow Y$ is expansive if and only if there exists $\beta \in \mathcal{G}$ such that for all distinct $x, y \in Y$ there exists $n \in \mathbb{Z}$ with $(f^n(x), f^n(y)) \notin \beta$. Since \mathcal{G} is the unique compatible uniform structure in Y , expansivity of homeomorphism $f : Y \rightarrow Y$ does not depends on ρ and we may choose any compatible metric on Y .

Consider the equivalence relation \sim_φ on \mathbb{N} as in Remark 3. We prove $\sigma_\varphi : X^\mathbb{N} \rightarrow X^\mathbb{N}$ is expansive if and only if $\frac{\mathbb{N}}{\sim_\varphi} = \{\frac{\alpha}{\sim_\varphi} : \alpha \in \mathbb{N}\}$ is finite. Also using Remark 4 equip $\{1, \dots, k\}^\mathbb{N}$ with metric

$$d((x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}}) = \sum_{n \in \mathbb{N}} \frac{\delta(x_n, y_n)}{2^n} \quad (*)$$

for $(x_n)_{n \in \mathbb{N}}, (y_n)_{n \in \mathbb{N}} \in \{1, \dots, k\}^\mathbb{N}$, where:

$$\delta(z, w) = \begin{cases} 0 & z = w, \\ 1 & z \neq w. \end{cases}$$

So $(\{1, \dots, k\}^\mathbb{N}, d)$ is a compact metric space (metric topology on $\{1, \dots, k\}^\mathbb{N}$ induced from d , coincides with product topology on $\{1, \dots, k\}^\mathbb{N}$ (see [7])).

LEMMA 2.1. *If $\frac{\mathbb{N}}{\sim_\varphi} = \{\frac{\alpha_1}{\sim_\varphi}, \dots, \frac{\alpha_s}{\sim_\varphi}\}$, then for all distinct $x, y \in \{1, \dots, k\}^\mathbb{N}$ there exists $n \in \mathbb{N}$ such that $d(f^n(x), f^n(y)) \geq \frac{1}{2^{\max(\alpha_1, \dots, \alpha_s)}}$ (consider metric d on $\{1, \dots, k\}^\mathbb{N}$ as in (*)).*

Proof. Consider distinct $x = (x_n)_{n \in \mathbb{N}}, y = (y_n)_{n \in \mathbb{N}} \in \{1, \dots, k\}^\mathbb{N}$. There exists $m \in \mathbb{N}$ with $x_m \neq y_m$, there exists $r \in \{1, \dots, s\}$ with $m \in \frac{\alpha_r}{\sim_\varphi}$, so there exists $k \in \mathbb{Z}$ with $\varphi^k(\alpha_r) = m$. Suppose $(z_n)_{n \in \mathbb{N}} := \sigma_\varphi^k(x) = (x_{\varphi^k(n)})_{n \in \mathbb{N}}$ and $(w_n)_{n \in \mathbb{N}} := \sigma_\varphi^k(y) = (y_{\varphi^k(n)})_{n \in \mathbb{N}}$. Thus

$$\begin{aligned} d(\sigma_\varphi^k(x), \sigma_\varphi^k(y)) &= d((z_n)_{n \in \mathbb{N}}, (w_n)_{n \in \mathbb{N}}) \\ &\geq \frac{\delta(z_{\alpha_r}, w_{\alpha_r})}{2^{\alpha_r}} = \frac{\delta(x_{\varphi^k(\alpha_r)}, y_{\varphi^k(\alpha_r)})}{2^{\alpha_r}} \\ &= \frac{\delta(x_m, y_m)}{2^{\alpha_r}} = \frac{1}{2^{\alpha_r}} \geq \frac{1}{2^{\max(\alpha_1, \dots, \alpha_s)}} \end{aligned}$$

which completes the proof. \square

COROLLARY 2.1. *If $\frac{\mathbb{N}}{\sim_\varphi}$ is finite, then $\sigma_\varphi : \{1, \dots, k\}^\mathbb{N} \rightarrow \{1, \dots, k\}^\mathbb{N}$ is expansive.*

Proof. If $\frac{\mathbb{N}}{\sim_\varphi} = \{\frac{\alpha_1}{\sim_\varphi}, \dots, \frac{\alpha_s}{\sim_\varphi}\}$ choose $\mu \in (0, \frac{1}{2^{\max(\alpha_1, \dots, \alpha_s)}})$. By Lemma 2.1 for all distinct $x, y \in \{1, \dots, k\}^\mathbb{N}$ there exists $n \in \mathbb{Z}$ with $d(\sigma_\varphi^n(x), \sigma_\varphi^n(y)) \geq \frac{1}{2^{\max(\alpha_1, \dots, \alpha_s)}} > \mu$ which leads to the desired result by Remark 4. \square

LEMMA 2.2. *If $\frac{\mathbb{N}}{\sim_\varphi}$ is infinite, then $\sigma_\varphi : \{1, \dots, k\}^\mathbb{N} \rightarrow \{1, \dots, k\}^\mathbb{N}$ is not expansive.*

Proof. Consider $\mu > 0$, then there exists $N \in \mathbb{N}$ such that $\sum_{n > N} \frac{1}{2^n} < \mu$. Since $\frac{\mathbb{N}}{\sim_\varphi}$ is infinite, there exists $m \in \mathbb{N}$ such that $\frac{m}{\sim_\varphi} \neq \frac{k}{\sim_\varphi}$ for all $k \in \{1, \dots, N\}$, i.e. $m \in \mathbb{N} \setminus (\frac{1}{\sim_\varphi} \cup \dots \cup \frac{N}{\sim_\varphi})$, and $\frac{m}{\sim_\varphi} \subseteq \mathbb{N} \setminus (\frac{1}{\sim_\varphi} \cup \dots \cup \frac{N}{\sim_\varphi}) \subseteq \mathbb{N} \setminus \{1, \dots, N\}$ let $x_n = y_n = 1$ for all $n \in \mathbb{N} \setminus \{m\}$, $x_m = 1$ and $y_m = 2$. For $x = (x_n)_{n \in \mathbb{N}}, y = (y_n)_{n \in \mathbb{N}}$ for all $r \in \mathbb{Z}$ we have:

$$\begin{aligned} d(\sigma_\varphi^r(x), \sigma_\varphi^r(y)) &= d((x_{\varphi^r(n)})_{n \in \mathbb{N}}, (y_{\varphi^r(n)})_{n \in \mathbb{N}}) \\ &\leq \sum_{x_{\varphi^r(n)} \neq y_{\varphi^r(n)}} \frac{1}{2^n} = \sum_{\varphi^r(n)=m} \frac{1}{2^n} \leq \sum_{n \sim_\varphi m} \frac{1}{2^n} \leq \sum_{n > N} \frac{1}{2^n} < \mu. \end{aligned}$$

Hence we have:

$$\forall \mu > 0 \exists x \neq y \forall r \in \mathbb{Z} (d(f^r(x), f^r(y)) < \mu).$$

Using Remark 4, $\sigma_\varphi : \{1, \dots, k\}^{\mathbb{N}} \rightarrow \{1, \dots, k\}^{\mathbb{N}}$ is not expansive. \square

THEOREM 2.1. *For bijection $\varphi : \mathbb{N} \rightarrow \mathbb{N}$ and discrete set $\{1, \dots, k\}$ with $k \geq 2$, the generalized shift dynamical system $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_\varphi)$ is expansive if and only if $\frac{\mathbb{N}}{\sim_\varphi}$ is finite (i.e., there exists $n_1, \dots, n_s \in \mathbb{N}$ with $\mathbb{N} = \{\varphi^i(n_j) : j \in \{1, \dots, s\}, i \in \mathbb{Z}\}$).*

Proof. Use Corollary 2.1 and Lemma 2.2. \square

EXAMPLE 1. *Define $\varphi_1, \varphi_2 : \mathbb{N} \rightarrow \mathbb{N}$ with:*

$$\varphi_1(n) = \begin{cases} n+2 & n \text{ is odd} \\ n-2 & n > 2 \text{ is even} \\ 1 & n = 2 \end{cases} \quad \text{and} \quad \varphi_2(n) = \begin{cases} n+1 & n \text{ is odd} \\ n-1 & n \text{ is even} \end{cases}$$

then $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_{\varphi_1})$ is expansive, and $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_{\varphi_2})$ is not expansive, since $\frac{\mathbb{N}}{\sim_{\varphi_1}} = \{\mathbb{N}\}$ and $\frac{\mathbb{N}}{\sim_{\varphi_2}} = \{\{2n-1, 2n\} : n \in \mathbb{N}\}$.

3. e -CHAOTIC GENERALIZED SHIFT DYNAMICAL SYSTEM $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_\varphi)$

We call the dynamical system (Y, f) , e -chaotic, if it is expansive and the set of all periodic points (of $f : Y \rightarrow Y$) is dense in Y [9], we recall that $a \in Y$ is a periodic point of $f : Y \rightarrow Y$ if there exists $n \geq 1$ with $f^n(a) = a$.

REMARK 5. *If Y is a discrete topological space with at least two elements, Λ is a nonempty set and $\eta : \Lambda \rightarrow \Lambda$ is arbitrary, then the set of periodic points of $\sigma_\eta : Y^\Lambda \rightarrow Y^\Lambda$ ($\sigma_\eta((x_\alpha)_{\alpha \in \Lambda}) = (x_{\eta(\alpha)})_{\alpha \in \Lambda}$) is dense in Y^Λ if and only if $\eta : \Lambda \rightarrow \Lambda$ is one to one [4, Theorem 2.6].*

THEOREM 3.1 (main). *For bijection $\varphi : \mathbb{N} \rightarrow \mathbb{N}$ discrete set $\{1, \dots, k\}$ with $k \geq 2$, in the generalized shift dynamical system $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_\varphi)$, the following statements are equivalent:*

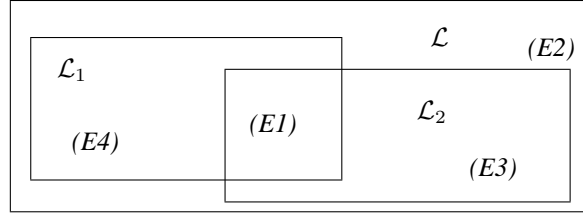
- $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_\varphi)$ is e -chaotic;
- $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_\varphi)$ is expansive;
- $\frac{\mathbb{N}}{\sim_\varphi}$ is finite (i.e., there exists $n_1, \dots, n_s \in \mathbb{N}$ with $\mathbb{N} = \{\varphi^i(n_j) : j \in \{1, \dots, s\}, i \in \mathbb{Z}\}$, or equivalently $\{\{\varphi^i(n) : i \in \mathbb{Z}\} : n \in \mathbb{N}\}$ is a finite partition of \mathbb{N}).

Proof. Use Remark 5 and Theorem 2.1. \square

EXAMPLE 2. *Using [4, Theorem 2.13], for discrete topological space Y with at least two elements and $\eta : \mathbb{N} \rightarrow \mathbb{N}$, the generalized shift dynamical system $(Y^{\mathbb{N}}, \sigma_\eta)$ is Devaney chaotic if and only if $\eta : \mathbb{N} \rightarrow \mathbb{N}$ is one to one without any periodic point. Let:*

- \mathcal{L} = the class of all generalized shift dynamical systems $(Y^{\mathbb{N}}, \sigma_\eta)$, where $\eta : \mathbb{N} \rightarrow \mathbb{N}$ is bijective.
- \mathcal{L}_1 = the class of all Devaney chaotic generalized shift dynamical systems $(Y^{\mathbb{N}}, \sigma_\eta)$, where $\eta : \mathbb{N} \rightarrow \mathbb{N}$ is bijective.
- \mathcal{L}_2 = the class of all e -chaotic generalized shift dynamical systems $(Y^{\mathbb{N}}, \sigma_\eta)$, where $\eta : \mathbb{N} \rightarrow \mathbb{N}$ is bijective.

We have the following diagram:



where:

- E1 is $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_{\varphi_1})$ as in Example 1;
- E2 is $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_{\varphi_2})$ as in Example 1;
- E3 is $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_{\varphi_3})$ for $\varphi_3 : \mathbb{N} \rightarrow \mathbb{N}$ with $(k \geq 2)$:

$$\varphi_3(n) = \begin{cases} 1 & n = 1, \\ \varphi_1(n - 1) + 1 & n > 1; \end{cases}$$

- E4 is $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_{\varphi_4})$ for $\varphi_4 : \mathbb{N} \rightarrow \mathbb{N}$ with $(k \geq 2)$ (suppose p_m is the m th prime number and $\mathbb{N} \setminus \{p_m^k : m, k \geq 1\} = \{w_1, w_2, \dots\}$ for $w_1 < w_2 < \dots$):

$$\varphi_4(n) = \begin{cases} p_m^{\varphi_1(k)} & n = p_m^k, \\ w_{\varphi_1(k)} & n = w_k. \end{cases}$$

4. MORE DETAILS ON EXPANSIVE GENERALIZED SHIFT DYNAMICAL SYSTEMS

Regarding previous sections, let's call the dynamical system $((Z, \mathcal{F}), f)$ with uniform phase space (Z, \mathcal{F}) and homeomorphism $f : Z \rightarrow Z$ *expansive* if there exists $\mu \in \mathcal{F}$ such that for all distinct $x, y \in Z$ there exists $n \in \mathbb{Z}$ with $(f^n(x), f^n(y)) \notin \mu$. In this section suppose (Y, \mathcal{K}) is a uniform Hausdorff space with at least two elements, Λ is a nonempty set and $\lambda : \Lambda \rightarrow \Lambda$ is an arbitrary map. It is well-known that product and subspaces of uniform spaces are uniformizable.

In this section we prove that if the generalized shift dynamical system $(Y^\Lambda, \sigma_\lambda)$ with bijection $\lambda : \Lambda \rightarrow \Lambda$ is expansive (with any compatible uniformity on Y^Λ , where Y^Λ equipped with product topology), then Λ is countable and $\{\{\lambda^n(\alpha) : n \in \mathbb{Z}\} : \alpha \in \Lambda\}$ is a finite partition of Λ .

COROLLARY 4.1. *Using Theorem 3.1 if M is countable, W is finite discrete with at least two elements and $\psi : M \rightarrow M$ is bijective, then the following statements are equivalent (note that W^M with product topology is a compact metrizable space):*

- (W^M, σ_ψ) is e—chaotic,
- (W^M, σ_ψ) is expansive,
- $\frac{M}{\sim_\psi}$ is finite.

THEOREM 4.1. *For bijection $\lambda : \Lambda \rightarrow \Lambda$ if the generalized shift dynamical system $(Y^\Lambda, \sigma_\lambda)$ is expansive, then Λ is countable and $\frac{\Lambda}{\sim_\lambda}$ is finite.*

Proof. First of all note that for all $\alpha \in \Lambda$, $\frac{\alpha}{\sim_\lambda} = \{\lambda^n(\alpha) : n \in \mathbb{Z}\}$ is countable. Suppose $\{\alpha_n\}_{n \geq 1}$ is a sequence in Λ and p, q are two distinct elements of Y . Let $M = \bigcup \{\frac{\alpha_n}{\sim_\lambda} : n \geq 1\}$. Since $(Y^\Lambda, \sigma_\lambda)$ is expansive, $(\{p, q\}^M, \sigma_{\lambda \upharpoonright_M})$ is expansive too. Since $\{p, q\}$ is a discrete set with two elements and M is countable, using Corollary 4.1, for $\psi = \lambda \upharpoonright_M$ the set $\frac{M}{\sim_\psi} (= \{\frac{\alpha_n}{\sim_\lambda} : n \geq 1\})$ is finite. Thus we don't have any infinite sequence in $\frac{\Lambda}{\sim_\lambda}$ and $\frac{\Lambda}{\sim_\lambda}$ is finite. Since $\frac{\Lambda}{\sim_\lambda}$ is finite and all $\frac{\alpha}{\sim_\lambda} (\in \frac{\Lambda}{\sim_\lambda})$ is countable, the set $\bigcup \frac{\Lambda}{\sim_\lambda} = \Lambda$ is countable too. \square

Positively expansive dynamical system. We call the dynamical system (Y, f) (or briefly $f : Y \rightarrow Y$) with compact metric space (Y, ρ) , *positively expansive* if there exists $\mu > 0$ such that for all distinct $x, y \in Y$ there exists $n \geq 0$ with $\rho(f^n(x), f^n(y)) > \mu$ [8]. It's evident that for homeomorphism $f : Y \rightarrow Y$, if (Y, f) is positively expansive, then it is expansive. Using the same method described in Remark 4 positively expansivity of continuous map $f : Y \rightarrow Y$ does not depends on ρ and we may choose any compatible metric on Y . Using the same proof as in Lemma 2.2, for arbitrary self-map $\mu : \mathbb{N} \rightarrow \mathbb{N}$, if the generalized shift dynamical system $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_\mu)$ is positively expansive, then $\frac{\mathbb{N}}{\sim_\mu}$ is finite. However for constant map $\mu : \mathbb{N} \rightarrow \mathbb{N}$ with $\mu(n) = 1$, the dynamical system $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_\mu)$ is not positively expansive, although $\frac{\mathbb{N}}{\sim_\mu}$ is finite. Moreover using Lemma 2.1 and Theorem 3.1 we have the following corollary.

COROLLARY 4.2. *For bijection $\varphi : \mathbb{N} \rightarrow \mathbb{N}$ and discrete set $\{1, \dots, k\}$ with $k \geq 2$, the generalized shift dynamical system $(\{1, \dots, k\}^{\mathbb{N}}, \sigma_\varphi)$ is expansive if and only if it is positively expansive.*

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