

## Improved Complexity of a Homotopy Method for Locating an Approximate Zero

Ioannis K. Argyros  
Department of Mathematical Sciences,  
Cameron University,  
Lawton, OK 73505, USA.  
Email: iargyros@cameron.edu

Santhosh George  
Department of Mathematical and Computational Sciences,  
NIT Karnataka,  
575025-India.  
Email:sgeorge@nitk.ac.in

Received: 25 August, 2017 / Accepted: 21 November, 2017 / Published online:  
18 January, 2018

**Abstract.** The goal of this study is to extend the applicability of a homotopy method for locating an approximate zero using Newton's method. The improvements are obtained using more precise Lipschitz-type functions than in earlier works and our new idea of restricted convergence regions. Moreover, these improvements are found under the same computational effort.

**AMS Subject Classifications:** 65G99, 65H10, 47H17, 49M15,

**Key words:** Approximate zero, Banach space, Homotopy method, Newton's method, local, semi-local convergence, Lipschitz-type conditions.

## 1 Introduction

The convergence region and error analysis of iterative methods are very pessimistic in general for both the semi-local and local case [1–5, 11–16]. The aim of the paper is to extend the convergence region using the homotopy method. This goal is achieved using the same Lipschitz-type functions as before [4, 6–10, 13]. We achieve this goal, since we find a more precise location for the Newton iterates leading to at least as tight Lipschitz-type functions [4, 6, 7]. Let  $F : D \subset \mathcal{B}_1 \longrightarrow \mathcal{B}_2$  be differentiable in the sense of Fréchet,  $D$  be a convex and open subset of  $\mathcal{B}_1$  and  $\mathcal{B}_1, \mathcal{B}_2$  be Banach spaces.

Let  $F'$  is one-to-one and onto, we introduce the Newton operator

$$N_F(x) := x - F'(x)^{-1}F(x) \tag{1.1}$$

and the corresponding Newton iteration

$$x_{n+1} = N_F(x_n) \text{ for all } n = 0, 1, 2, \dots \quad (1.2)$$

where  $x_0 \in D$  is an initial point. We are concerned with the problem of approximating a regular (to be precised in Section 2) solution  $w$  of

$$F(x) = 0 \quad (1.3)$$

utilizing a homotopy method of the form

$$\mathcal{H}(x, t) := F(x) - tF(x_0) \quad (1.4)$$

where  $x_0 \in D$  is a given initial point and  $t \in [0, 1]$ . Clearly this is a geometrical way of solving equation (1.3). Consider the line segment  $M = \{tF(x_0) : t \in [0, 1]\}$  and the set  $F^{-1}(M)$ . Suppose that  $F'(x_0)$  is one-to-one and onto. Then, it follows by the implicit function theorem applied in a neighbourhood of  $x_0$  that there exists a curve  $x(t)$  solving the equation  $F(x(t)) = tF(x_0)$  for  $t \in [1 - \varepsilon, 1]$  and  $\varepsilon > 0$ . This curve solves the initial value problem (IVP)

$$\dot{x}(t) = -DF(x(t))^{-1}F(x_0), \quad x(1) = x_0. \quad (1.5)$$

It is well known that (1.5) has no solution on  $[0, 1]$ , in general. But if it has a solution, one must follow  $x(t)$  (numerically), which is given by  $\mathcal{H}(x(t), t) = 0$  using the operator related to  $\mathcal{H}(\cdot, t)$ . That is consider the sequence  $\{s_n\}$  given by  $s_0 = 1 > s_1 > \dots > s_n > \dots > 0$  such that

$$x_{n+1} = N_{\mathcal{H}(\cdot, s_{n+1})}(x_k)$$

is an approximate zero of  $x(s_{n+1})$ , with

$$\mathcal{H}(x(s_{n+1}), s_{n+1}) = 0.$$

A convergence analysis of Newton sequence  $\{x_n\}$  was given in the elegant work by Guttierrez et al. [10]. Here, we improve their results as already mentioned previously.

The study is structured as: The convergence of Newton's method is presented in Section 2 whereas Section 3 contains the special cases. Finally, in Section 4, we present the numerical examples.

## 1 Convergence Analysis

We need the Definition of an approximate zero.

**Definition 1.1** [14] *A  $G$ -regular ball is open so that  $G'(x)$  is one-to-one and onto. A point  $x_0$  is a regular approximate zero of  $G$ , provided there exists a ball  $G$ -regular containing a zero  $w$  of  $G$  and a sequence  $\{x_n\}$  converging to  $w$ .*

Let  $L_0, \bar{L}, L : [0, +\infty) \rightarrow [0, +\infty)$  be continuous and non-decreasing functions. These functions are needed for the introduction of the Lipschitz conditions that follow (see (1.7), (1.9) and (1.11)). We shall also suppose that there exists  $z \in D$  so  $G'(z)$  is continuous, one-to-one, onto and  $G'(z)^{-1}$  exists. We need to introduce the following two Lipschitz conditions that follow.

**Definition 1.2** *The function  $G'(z)^{-1}G'$  is  $L_0$ -center Lipschitz at  $z$  if there exist positive quantities  $v_0$  and*

$$\gamma_0 := \gamma_0(G, z) \quad (1.6)$$

satisfying for  $a \in D$ ,  $\gamma_0(\|a - z\|) \leq v_0$

$$\|G'(z)^{-1}(G'(a) - G'(z))\| \leq \int_0^{\gamma_0\|a-z\|} L_0(\tau) d\tau. \quad (1.7)$$

**Definition 1.3** *The function  $G'(z)^{-1}G'$  is  $\bar{L}$ -center Lipschitz restricted at  $z$ , if there exist positive quantities  $\bar{v}$  and*

$$\bar{\gamma} := \bar{\gamma}(G, z) \quad (1.8)$$

satisfying for  $a, b \in D_0 := D \cap \bar{U}(z, \frac{\bar{v}}{\bar{\gamma}})$

$$\bar{\gamma}(\|a - z\| + \tau\|a - b\|) \leq \bar{v}$$

and

$$\|G'(z)^{-1}(G'((1 - \tau)a + \tau b) - G'(a))\| \leq \int_{\bar{\gamma}\|a-z\|}^{\bar{\gamma}(\|a-z\| + \tau\|b-a\|)} \bar{L}(\tau) d\tau \quad (1.9)$$

for all  $\tau \in [0, 1]$ .

**Definition 1.4** [10] *The function  $G'(y_0)^{-1}G'$  is  $L$ -center Lipschitz at  $z$  if there exist positive quantities  $v$  and*

$$\gamma := \gamma(G, z) \quad (1.10)$$

satisfying for  $a, b \in D$

$$\gamma(\|a - z\| + \tau\|a - b\|) \leq v$$

and

$$\|G'(z)^{-1}(G'((1 - \tau)a + \tau b) - G'(a))\| \leq \int_{\gamma\|a-z\|}^{\gamma(\|a-z\| + \tau\|b-a\|)} L(\tau) d\tau \quad (1.11)$$

for each  $\tau \in [0, 1]$ .

**REMARK 1.5** *Notice that (1.11) implies (1.7) and (1.9). We can certainly take  $v_0 = v = \bar{v}$ ,  $L_0(\tau) = L(\tau) = \bar{L}(\tau)$  for each  $\tau \geq 0$ , so for all  $\tau \in [0, v]$*

$$\gamma_0(\tau) \leq \gamma(\tau) \quad (1.12)$$

and

$$\bar{\gamma}(\tau) \leq \gamma(\tau), \quad (1.13)$$

since  $D_0 \subset D$ .

In what follows we shall assume that

$$\gamma_0(\tau) \leq \bar{\gamma}(\tau). \quad (1.14)$$

If instead of (1.14)

$$\bar{\gamma}(\tau) \leq \gamma_0(\tau), \quad (1.15)$$

holds then the following results are true with  $\bar{L}$  replacing  $L_0$  in all of them.

**LEMMA 1.6** *Suppose that  $v_0$  is the least positive number such that*

$$\int_0^{v_0} L_0(\tau) d\tau = 1. \quad (1.16)$$

*Then  $F'(x)$  is one-to-one, onto and*

$$\|F'(x)^{-1}F'(z)\| \leq \left(1 - \int_0^{\gamma_0\|x-z\|} L_0(\tau) d\tau\right)^{-1} \quad \text{for all } x \in U\left(z, \frac{v_0}{\gamma_0}\right). \quad (1.17)$$

*The set  $U\left(z, \frac{v_0}{\gamma_0}\right)$  is called the  $\gamma_0$ -ball of  $z$ . We define similarly, the  $\bar{\gamma}$  and  $\gamma$ -balls. As in [10], we assume the existence of  $\bar{\varphi} : [0, \bar{v}) \rightarrow [0, +\infty)$  satisfying  $\bar{\varphi}(0) = 1$ , where*

$$\bar{\gamma}(F, x) = \bar{\varphi}(\bar{\gamma}(F, z)\|x - z\|)\bar{\gamma} \quad \text{for each } x \text{ in } U\left(z, \frac{\bar{v}}{\bar{\gamma}}\right). \quad (1.18)$$

*Moreover, for  $b = b(F, z) := \|F'(z)^{-1}F'(z)\|$  we set*

$$\bar{\alpha} := \bar{\alpha}(F, z) := \bar{\gamma}\bar{b}. \quad (1.19)$$

By simply using (1.17) instead of the less precise estimate (since  $\gamma_0(\tau) \leq \gamma(\tau)$ )

$$\|F'(x)^{-1}F'(x_0)\| \leq \left(1 - \int_0^{\gamma_0\|x-x_0\|} L(\tau) d\tau\right)^{-1} \quad \text{for all } x \in U\left(x_0, \frac{v}{\gamma}\right). \quad (1.20)$$

as well as  $\bar{\gamma}, \bar{v}$  instead of  $\gamma, v$ , respectively, we can reproduce the proofs of the results of [10] in this setting.

The following result improves Theorem 1 in [10] which in turn generalizes the corresponding result by Meyer [13].

**THEOREM 1.7** *Suppose:  $F'(x_0)^{-1}F$  is  $\bar{L}$ - and  $L_0$ - Lipschitz restricted at  $x_0 \in D$ ;*

$$\bar{\alpha}(F, x_0) \leq \int_0^{\bar{v}} \bar{L}(\tau) \tau d\tau \quad (1.21)$$

*and*

$$\bar{U}(x_0, \bar{v}) \subseteq D, \quad (1.22)$$

*where  $\bar{\alpha}$  is given by (1.19) and  $\bar{v}$  is the smallest positive number such that*

$$\int_0^{\bar{v}} \bar{L}(\tau) d\tau = 1. \quad (1.23)$$

Then, the solution of the IVP (1.5) exists in  $U(x_0, \frac{v_1}{\bar{\gamma}})$  for each  $t \in [0, 1]$ , where  $\bar{v}_1$  is the first positive root of  $g_{\bar{a}}(t)$  less than or equal to  $u_{\bar{L}/\bar{c}}$  where  $g_{\bar{a}}(t) = \bar{a} - t + \int_0^t \bar{L}(\tau)(t - \tau)d\tau$ . Therefore,  $x(0)$  is a solution of equation (1.3).

Condition (1.21) is the usual Newton-Kantorovich type criterion [2, 3, 15].

**REMARK 1.8** If  $L_0(s) \geq \bar{L}(s)$  for all  $s \in [0, \bar{v}]$ , then the results of Theorem 1.7 hold with  $\bar{L}$  replacing  $L$ .

The Theorem 1.7 does not apply, if  $\bar{\alpha} > \int_0^{\bar{v}} \bar{L}(s)ds$ . That is why as in [10], we suppose that the solution of the IVP (1.5) is inside the  $\bar{\gamma}$ -ball of  $x_0$ . Then, we ask: How many  $k$ -steps are needed to approximate the zero  $x_k$  of  $F = h(., 0)$ ?

**THEOREM 1.9** Let  $x_0$  be an element of the  $\bar{\gamma}$ -ball of  $z$ . Set  $v^* = \bar{\gamma}\|x_0 - z\|$  for  $0 \leq u < \bar{v}$ , where  $\bar{v}$  satisfies (1.23). Define function  $\bar{q}$  on  $[0, \bar{v}]$  by

$$\bar{q}(t) = \frac{\int_0^t \bar{L}(\tau)d\tau}{t(1 - \int_0^t L_0(\tau)d\tau)}. \quad (1.24)$$

Let  $u_{\bar{L}}$  be such that

$$\bar{q}(u_{\bar{L}}) = 1. \quad (1.25)$$

Let  $\bar{c} \geq 1$  and define function  $g_{\bar{a}}$  on  $[0, \bar{v}]$  by

$$g_{\bar{a}}(t) = \bar{a} - t + \int_0^t \bar{L}(\tau)(t - \tau)d\tau, \quad (1.26)$$

so that

$$\min\{u_{\bar{L}/\bar{c}} - \int_0^{u_{\bar{L}/\bar{c}}} \bar{L}(\tau)(u_{\bar{L}/\bar{c}} - \tau)d\tau, \int_0^{\bar{v}} \bar{L}(\tau)\tau d\tau\} \geq \bar{a} \quad (1.27)$$

with the smallest positive solution of equation  $g_{\bar{a}}(t) = 0$  is not exceeding  $u_{\bar{L}/\bar{c}}$ . Set

$$p = \frac{\bar{\varphi}(u)(\bar{\alpha} + \int_0^{v^*} \bar{L}(\tau)(v^* - \tau)d\tau + v^*)}{(1 - \int_0^{u_{\bar{L}/\bar{c}}} L_0(\tau)d\tau)(1 - \int_0^u L_0(\tau)d\tau)}$$

$$q = \frac{\int_0^{u_{\bar{L}/\bar{c}}} \bar{L}(\tau)(u_{\bar{L}/\bar{c}} - \tau)d\tau + u_{\bar{L}/\bar{c}}}{1 - \int_0^{u_{\bar{L}/\bar{c}}} L_0(\tau)d\tau},$$

where  $\bar{\varphi}$  is given in (1.18). Moreover, suppose  $x(t)$  is the solution of the IVP is inside the  $\bar{\gamma}$ -ball of  $z$ . Let us also define sequence  $\{s_n\}$  by

$$s_0 = 1, s_n > 0, s_{n-1} - s_n > s_n - s_{n+1} > 0, n \geq 0, \lim_{n \rightarrow +\infty} s_n = 0, \quad (1.28)$$

where

$$s_1 = 1 - \frac{1 - \int_0^u L_0(\tau)d\tau}{\bar{\varphi}(u)(\bar{\alpha} + \int_0^{v^*} \bar{L}(\tau)(v^* - \tau)d\tau + v^*)}.$$

Set  $w_n$  such that  $F(w_n) = s_n F(x_0)$ . Then, the following assertions hold:

(i) Points  $w_n$  and  $w_{n+1}$ , are such that

$$\bar{\gamma}\varphi(u)\|w_{n+1} - w_n\| \leq \bar{a}.$$

(ii) Newton sequence  $\{x_n\}$  generated by (1.28) and  $w_n$  are such that

$$\bar{\gamma}\varphi(v^*)\|x_n - w_n\| \leq u_{\bar{L}/\bar{c}}.$$

(iii) Set  $\bar{N} = \frac{\int_0^{\bar{v}} \bar{L}(\tau)\tau d\tau - q}{p}$ . The steps  $n$  required for  $x_n$  to be an approximate zero of  $w_n$  exceeds or is equal to

$$\left\lceil \frac{1 - \bar{N}}{1 - s_1} \right\rceil, \text{ if } s_n := \max\{0, 1 - n(1 - s_1)\},$$

$$\left\lceil \frac{\log \bar{N}}{\log s_1} \right\rceil, \text{ if } s_n := s_1^n$$

$$\left\lceil \log_2 \left( \frac{\log \bar{N}}{\log s_1} + 1 \right) \right\rceil, \text{ if } s_n := s_1^{2^k - 1}.$$

$$\|x_n - \bar{w}\| \leq \bar{q}(\bar{u})^{2^n - 1} \|x_0 - \bar{w}\|,$$

where  $\bar{u} = \gamma(F, \bar{w})\|x_0 - \bar{w}\| < u_{\bar{L}}$  and  $\bar{q}$  is given in (1.24).

**REMARK 1.10** If  $L = L_0 = \bar{L}$ ,  $\gamma_0 = \gamma = \bar{\gamma}$ , then the preceding items coincide with the ones in [10]. But, if (1.12) or (1.8) hold as strict inequalities, then the new results constitute an improvement over the ones in [10]. These improvements are deduced using the same effort as in [10], because finding function  $L$  requires finding functions  $L_0$  and  $\bar{L}$ . If  $L_0 > \bar{L}$ , then, the preceding results hold with  $\bar{L}$  replacing  $L_0$ .

## 2 Special Cases

We consider specializations of the preceding results in the general (Kantorovich) case  $\bar{L}(s) = 1$  and the analytic case  $\bar{L}(s) = \frac{2}{(1-s)^3}$ , respectively. Examples, where (1.14) and (1.15) hold as strict inequalities in the Kantorovich case can be found in [2, 3] whereas the examples in the analytic case can be found in [4]. To avoid repetitions, we refer the reader to [10], where  $\alpha(F, x_0), \varphi, v, N, L$  are replaced by  $\bar{\alpha}(F, x_0), \bar{\varphi}, u, \bar{N}, \bar{L}$ , respectively.

Next, we present the  $\alpha$  and  $\gamma$  Theorems improving the works in [10] which in turn improved the works by X. Wang [16] and Traub and Wozniakowski [15], respectively.

**THEOREM 2.1** Suppose:  $F'(x_0)^{-1}F$  is  $\bar{L}$  and  $L_0$ -center-Lipschitz restricted at  $x_0$ ;

$$\bar{\alpha}(F, x_0) \leq \int_0^{\bar{v}} \bar{L}(\tau)\tau d\tau,$$

where  $\bar{v}$  is given in (1.23). Specialize function  $\bar{g}_{\alpha(F, x_0)}$  by

$$\bar{g}_{\alpha(F, x_0)}(t) := \bar{g}(t) = \bar{\alpha}(F, x_0) - t + \int_0^t \bar{L}(\tau)(t - \tau) d\tau. \quad (2.1)$$

Then, the following items hold

- (i) There exist  $\rho_1, \rho_2 \in \mathbb{R}$  with  $\rho_1 \neq \rho_2$  such that  $\bar{g}(\rho_1) = \bar{g}(\rho_2) = 0$  with  $\bar{g}$  strictly convex and

$$\bar{g}(t) = (t - \rho_1)(t - \rho_2)\psi(t),$$

where

$$\psi(t) = \int_0^1 \int_0^1 \theta(\bar{L}(1 - \theta) + \theta s \rho_2 + \theta \tau t) d\tau d\theta.$$

and for  $r_0 = 0$ ,  $\lim_{n \rightarrow +\infty} r_n = \lim_{n \rightarrow +\infty} N_{\bar{g}}(r_{n-1}) = \bar{v}_1$ .

- (ii) Equation  $F(x) = 0$  has a solution  $\bar{w}$  which is unique in  $U(x_0, \frac{\bar{v}}{\bar{\gamma}(F, x_0)})$ .  
 (iii) Newton sequence  $\{x_n\}$  defined by  $x_{n+1} = N_F(x_n)$  exists, stays in  $\bar{U}(x_0, \frac{\rho_1}{\bar{\gamma}(F, x_0)})$  and converges to  $\bar{w}$ , so that

$$\|x_n - \bar{w}\| \leq \|r_n - \rho_1\|$$

- (iv) If  $\bar{g}(t) \geq \frac{\bar{\alpha}(F, x_0)}{\rho_1 \rho_2}$ , then

$$\|x_n - \bar{w}\| \leq \frac{1}{\bar{\gamma}(F, x_0) z^n} \left( \frac{\rho_1}{\rho_2} \right)^{2^n - 1} \rho_1.$$

**THEOREM 2.2** Suppose:

- (i)  $\bar{w}$  solves  $F(x) = 0$  and is a regular solution:  
 (ii)  $F'(\bar{w})^{-1}F'(\bar{w})$  is  $\bar{L}$  and  $L_0$  center Lipschitz restricted for all  $x \in U(\bar{w}, \frac{\bar{v}}{\bar{\gamma}(F, \bar{w})})$ .  
 Then, Newton sequence  $\{x_n\}$  generated by  $x_0 = x, x_{n+1} = N_F(x_n)$  converges to  $\bar{w}$  for all  $x \in U(\bar{w}, \frac{u_{\bar{L}}}{\bar{\gamma}(F, \bar{w})})$ , where  $u_{\bar{L}}$  is given in (1.25). Moreover, we have the following:

$$\|x_n - \bar{w}\| \leq \bar{q}(\bar{u})^{2^n - 1} \|x_0 - \bar{w}\|.$$

**REMARK 2.3** If  $L_0 = L = \bar{L}, \gamma_0 = \gamma = \bar{\gamma}$ , the two preceding results reduce to Theorem 3 and Theorem 4 in [10], respectively, i.e., if (1.14) or (1.15) hold as strict inequalities, then the earlier results are improved (see also the numerical examples).

### 3 Numerical examples

We provide two examples for the Kantorovich case, where function has no positive roots. Hence the older results can not apply, but function  $\bar{g}$  has roots, so the new results apply to solve equations.

**EXAMPLE 3.1** Let  $\mathcal{B}_1 = \mathcal{B}_2 = \mathbb{R}$ ,  $x_0 = 1$ ,  $D = \{x : |x - x_0| \leq \lambda\}$ ,  $\lambda \in [0, 1/2)$  and  $F$  defined by

$$F(x) = x^3 - \lambda. \quad (3.2)$$

Then, for  $L_0(\tau) = L(\tau) = \bar{L}(\tau) = 1$ ,  $v_0 = \bar{v} = v = 1$ , we have

$$\bar{b} = b = \frac{1 - \lambda}{3}, \gamma_0(\tau) = 3 - \lambda, \gamma(\tau) = 2(2 - \lambda) \text{ and } \bar{\gamma}(\tau) = 2\left(1 + \frac{1}{3 - \lambda}\right).$$

Notice that

$$\gamma_0 < \gamma < \bar{\gamma}.$$

The functions  $g$  and  $\bar{g}$  are then given, respectively by

$$g(t) = \frac{t^2}{2} - t + \frac{2}{3}(1 - \lambda)(2 - \lambda)$$

and

$$\bar{g}(t) = \frac{t^2}{2} - t + \frac{2}{3}(1 - \lambda)\left(1 + \frac{1}{3 - \lambda}\right).$$

The Newton-Kantorovich condition (i.e., the discriminant  $d_g$  of  $g$ ) is given by

$$d_g = 1 - \frac{4}{3}(1 - \lambda)(2 - \lambda) < 0 \text{ for each } \lambda \in [0, 1/2) \quad (3.3)$$

so function  $g$  has not positive roots. However, function  $\bar{g}$  has positive roots, since the discriminant

$$d_{\bar{g}} = 1 - \frac{4}{3}(1 - \lambda)\left(1 + \frac{1}{3 - \lambda}\right) > 0 \text{ for each } \lambda \in I = [0.4619832, 1/2). \quad (3.4)$$

Therefore, our Theorem 2.1 can be used to solve equation  $F(x) = 0$  for all  $\lambda \in I$ .

**EXAMPLE 3.2** Let  $\mathcal{B}_1 = \mathcal{B}_2 = \mathcal{C}[0, 1]$ . Let  $D = \{x \in \mathcal{B}_1 : \|x\| \leq R\}$  for  $R > 0$ . Define  $F$  on  $D$  by

$$F(x)(s) = x(s) - f(s) - \delta \int_0^1 K(s, t)x(t)^3 dt, x \in \mathcal{B}_1, s \in [0, 1], \quad (3.5)$$

where  $f \in \mathcal{B}_1$  is a fixed function and  $\lambda$  is given by

$$K(s, t) = \begin{cases} (1 - s)t, & \text{if } t \leq s, \\ s(1 - t), & \text{if } s \leq t. \end{cases}$$

Then, for each  $x \in D$ ,  $F'(x)$  is given by

$$[F'(x)(v)](s) = v(s) - 3\delta \int_0^1 K(s,t)x(t)^2v(t)dt, v \in X, s \in [0, 1].$$

Set  $x_0(s) = f(s) = 1$ . Then, we have  $\|I - F'(x_0)\| \leq 3|\delta|/8$  if  $|\delta| < 8/3$ , then  $F'(x_0)^{-1}$  exists and

$$\|F'(x_0)^{-1}\| \leq \frac{8}{8 - 3|\delta|}.$$

Moreover,

$$\|F(x_0)\| \leq \frac{|\delta|}{8},$$

so

$$b = \|F'(x_0)^{-1}F(x_0)\| \leq \frac{|\delta|}{8 - 3|\delta|}.$$

Furthermore, for  $x, y \in D$ , we have

$$\|F'(x) - F'(y)\| \leq \frac{1 + 3|\delta|\|x + y\|}{8}\|x - y\| \leq \frac{1 + 6R|\delta|}{8}\|x - y\|$$

and

$$\|F'(x) - F'(1)\| \leq \frac{1 + 3|\delta|(\|x\| + 1)}{8}\|x - 1\| \leq \frac{1 + 3|\delta|(1 + R)}{8}\|x - 1\|.$$

Let  $\delta = 1.175$  and  $R = 2$ , we have  $b = 0.26257\dots$ ,  $\bar{\gamma}(\tau) = 2.76875\dots$ ,  $\gamma_0(\tau) = 1.8875\dots$  and  $\gamma(\tau) = 1.47314\dots$ ,  $v_0 = \bar{v} = v = 1$ . Using these values, we get that the discriminant  $d_g$  of  $g$  is

$$d_g = 1 - 1.02688 < 0,$$

but the discriminant  $d_{\bar{g}}$  of  $\bar{g}$  is

$$d_{\bar{g}} = 1 - 0.986217 > 0.$$

Hence,  $\lim_{n \rightarrow \infty} x_n = x_*$  by Theorem 2.1, where  $x_*$  is a solution of equation  $F(x)(s) = 0$ , where  $F$  is given by (3.5).

## References

- [1] E. L. Allgower and K. George, *Numerical continuation methods*, **33**, Springer, Berlin 1990.
- [2] I. K. Argyros, *Computational theory of iterative methods*. Series: Studies in Computational Mathematics, 15, Editors: C. K. Chui and L. Wuytack, Elsevier Publ. Co. New York, U. S. A, 2007.
- [3] I. K. Argyros and S. Hilout, *Weaker conditions for the convergence of Newton's method*, J. Complexity, **28**, (2012) 364–387.

- [4] I. K. Argyros and S. George, *Extending the applicability of Newton's method using Wang's- Smale's  $\alpha$ -theory*, Carpathian Journal of Mathematics, **33**, No. 1 (2017) 27-33.
- [5] I. K. Argyros and S. George, *Expanding the Convergence Domain of Newtonlike Methods and Applications in Banach Space*, Punjab Univ. J. Math. Vol. **47**, No. 1 (2015) 1-13
- [6] C. Beltran and A. Leykin, *Certified numerical homotopy tracking*, Exp. Math. **21**, No. 1 (2012) 69–83.
- [7] A. Cauchy, *Sur la determination approximative des racines d'une equation algebrique on transcendante In:Lecons sur le Calcul Differentiel*, Bure freres, Paris, (1829) 573–609.
- [8] J. P. Dedieu, G. Malajovich and M. Shub, *Adaptive step-size selection for homotopy methods to solve polynomial equations*, IMA J. Numer. Anal. **33**, No. 1 (2013) 1-29.
- [9] J. B. J Fourier, *Analyse des equations determincees*, Firmin Didot, Paris **1**, (1831).
- [10] J. M. Gutiérrez, A. A. Magrenán and J. C. Yakoubsohn, *Complexity of a Homotopy method at the neighborhood of a zero*, Springer International Publishing Switzerland, 2016, S. Amat, S. Busquier, eds. Advances in Iterative methods for nonlinear equations, SEMA SIMAI Springer Series, 10, Pages 147.
- [11] A. A. Magrénán, *Different anomalies in a Jarratt family of iterative root finding methods*, Appl. Math. Comput. **233**, (2014) 29-38.
- [12] A. A. Magrénán, *A new tool to study real dynamics: The convergence plane*, Appl. Math. Comput. **248**, (2014) 29-38.
- [13] G. H. Meyer, *On solving nonlinear equations with a one-parameter operator imbedding*, SIAM J. Numer. Anal. **5**, No. 4 (1968) 739-752.
- [14] S. Smale, *Newton's method estimates from data at one point. In:The merging of Discipline New Directions in Pure, Applied and Computational Mathematics (Laramie, Wyo, 1985), (1986), 185-196.*
- [15] J. F. Traub and H. Wozniakowski, *Convergence and Complexity of Newton iteration for operator equations*, J. ACM, **26**, No. 2 (1979) 250-258.
- [16] W. Xinghua, *Convergence of Newton's method and uniqueness of the solution of equations in Banach space*, IMA J. Numer. Anal. **20**, No. 1 (2000) 123-134.